

Chapter III

Euclidean vector spaces

$n \in \mathbb{N}$. III.1. Vectors

Def 102. The set of ordered n -tuples of real numbers is called n -space and denoted by \mathbb{R}^n , i.e.

$$\mathbb{R}^n = \{ (x_1, \dots, x_n) \mid x_1, \dots, x_n \in \mathbb{R} \}$$

coordinates of the point

We can view \mathbb{R}^n in two ways.

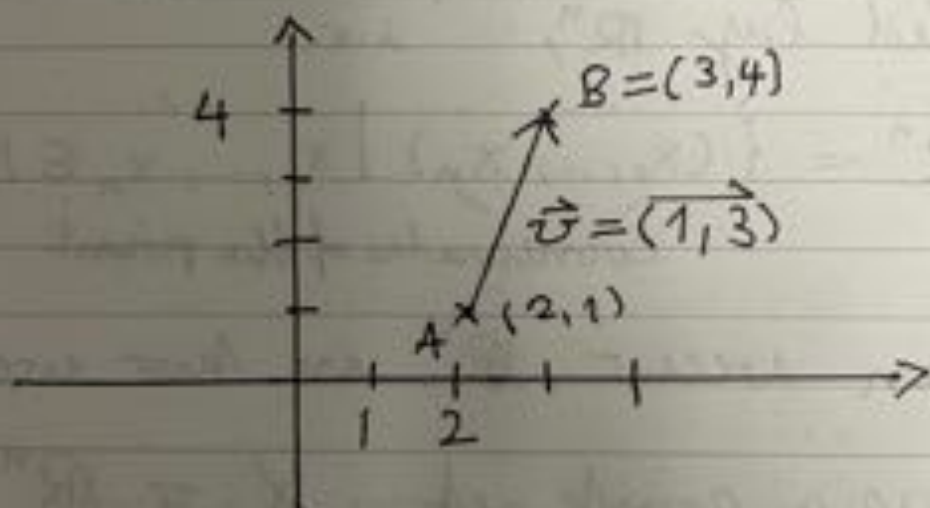
- as a point set $X := \mathbb{R}^n$
We will write capital letters for points: $A = (a_1, \dots, a_n) \in \mathbb{R}^n$.

- as a set of vectors $V := \mathbb{R}^n$,
 $\vec{v} = (v_1, \dots, v_n) \in V$.
 v_1, \dots, v_n are called the components of \vec{v} .

We can map a point $A \in X$
to another point using a vector
 $\vec{v} \in V$; "we translate A along \vec{v} "

$$t_{\vec{v}} : X \longrightarrow X$$

$$t_{\vec{v}}(A) := B = (a_1 + v_1, \dots, a_n + v_n)$$



$$t_{(1,3)}(A) = B$$

We can represent a vector
by a directed segment, which
consists of

- an "initial point" A
- a "terminal point" B
- and the vector

$$\vec{AB} = (b_1 - a_1, \dots, b_n - a_n)$$

Notation 103: Sometimes we write a vector using a column

$$\vec{v} = \begin{pmatrix} v_1 \\ \vdots \\ v_n \end{pmatrix}$$

Remark 104: Points are just points. Vectors are used to translate points. So we need a length and a direction.

Def 104: Given $\vec{v} = (v_1, \dots, v_n) \in V = \mathbb{R}^n$, the value

$$\|\vec{v}\| := \sqrt{v_1^2 + v_2^2 + \dots + v_n^2}$$

is called the norm (length, magnitude) of \vec{v} .

Example 105: (a) $\vec{v} = (1, 3) \in \mathbb{R}^2$

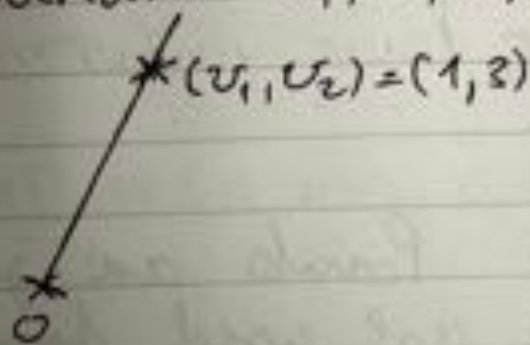
$$\|\vec{v}\| = \sqrt{1+9} = \sqrt{10}$$

$$\|(2, -1, 3, 4, 0, 1)\| = (4+1+9+16+1)^{1/2} = \sqrt{31}$$

for $\vec{w} = (2, -1, 3, 4, 0, 1) \in \mathbb{R}^6$

114+3

The direction is given by
the ray starting at $0 \in \mathbb{R}^n$
going through the point
with coordinates v_1, \dots, v_n .



III 2. Vector space structures on $V = \mathbb{R}^n$

We have two structures on V :

(1) $+$: $V \times V \longrightarrow V$ (an addition)

defined via

$$\vec{v} + \vec{w} := (v_1 + w_1, v_2 + w_2, \dots, v_n + w_n)$$

and

(2) \cdot : $\mathbb{R} \times V \longrightarrow V$ (a scalar multiplication)

via

$$\lambda \cdot \vec{v} := (\lambda v_1, \dots, \lambda v_n)$$

$\begin{pmatrix} 2 \\ 2 \end{pmatrix} + \begin{pmatrix} -1 \\ 2 \end{pmatrix} = \begin{pmatrix} 1 \\ 4 \end{pmatrix}$

$\begin{pmatrix} 4 \\ 4 \end{pmatrix} = 2 \begin{pmatrix} 2 \\ 2 \end{pmatrix}$

We recall

Prop 106: $(V, +, \cdot)$ satisfies the following

properties:

(1) (com +) $\vec{v} + \vec{w} = \vec{w} + \vec{v} \quad \forall \vec{v}, \vec{w} \in V$

"commutativity of +"

(2) (ass +) $(\vec{v} + \vec{w}) + \vec{u} = \vec{v} + (\vec{w} + \vec{u}) \quad \forall \vec{u}, \vec{v}, \vec{w} \in V$

"associativity of +"

(over $0+$) The element $\vec{0} = (0, \dots, 0)$ satisfies $\vec{v} + \vec{0} = \vec{0} + \vec{v} = \vec{v} \quad \forall \vec{v} \in V$

~~dist~~ "existence of a neutral element"

(inv $+$) For every $\vec{v} \in V$ there exists a $\vec{w} \in V$ such that $\vec{v} + \vec{w} = \vec{w} + \vec{v} = \vec{0}$.

"existence of an inverse"

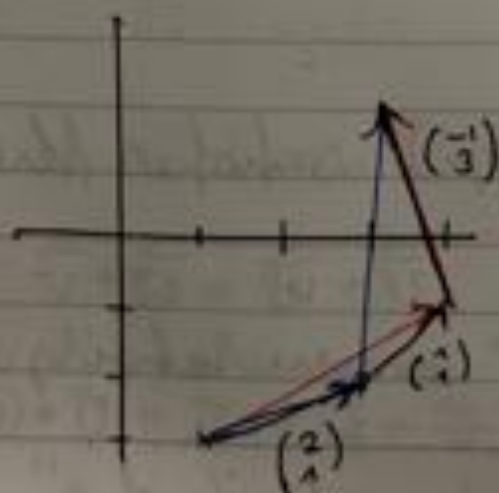
(2) (l dist, $\cdot, +$) $\forall \lambda \in \mathbb{R} \quad \forall \vec{v}, \vec{w} \in V$:
 $\lambda(\vec{v} + \vec{w}) = (\lambda\vec{v}) + (\lambda\vec{w})$.

(r dist, $+\mathbb{R}$) $\forall \lambda_1, \lambda_2 \in \mathbb{R} \quad \forall \vec{v} \in V$:
 $(\lambda_1 + \lambda_2)\vec{v} = (\lambda_1\vec{v}) + (\lambda_2\vec{v})$

(ass, \mathbb{R}) $\forall \lambda_1, \lambda_2 \in \mathbb{R} \quad \forall \vec{v} \in V$:
 $(\lambda_1 \mathbb{R} \lambda_2) \cdot \vec{v} = \lambda_1 (\lambda_2 \vec{v})$

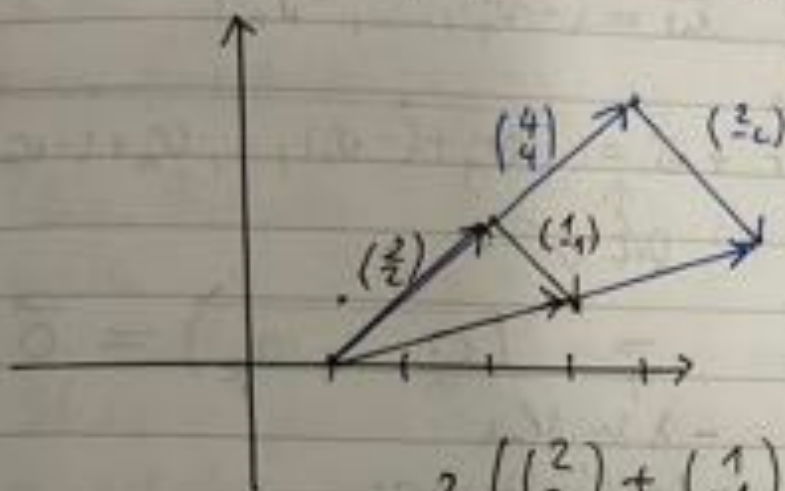
(unit, \cdot) $1 \cdot \vec{v} = \vec{v} \quad \forall \vec{v}$

Example 107: (a) For $(\text{ass}, +)$:



$$\begin{aligned} & \begin{pmatrix} 2 \\ 1 \end{pmatrix} + \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix} + \begin{pmatrix} -1 \\ 3 \end{pmatrix} \right) \\ &= \left(\begin{pmatrix} 2 \\ 1 \end{pmatrix} + \begin{pmatrix} 1 \\ 1 \end{pmatrix} \right) + \begin{pmatrix} -1 \\ 3 \end{pmatrix} \\ & \quad \begin{pmatrix} 3 \\ 2 \end{pmatrix} \end{aligned}$$

(b) For $(\text{dist}, \cdot, +)$ "left distributivity".



$$2 \left(\begin{pmatrix} 2 \\ 2 \end{pmatrix} + \begin{pmatrix} 1 \\ -1 \end{pmatrix} \right) = 2 \begin{pmatrix} 3 \\ 1 \end{pmatrix} = \begin{pmatrix} 6 \\ 2 \end{pmatrix}$$

$$2 \begin{pmatrix} 2 \\ 2 \end{pmatrix} + 2 \begin{pmatrix} 1 \\ -1 \end{pmatrix} = \begin{pmatrix} 4 \\ 4 \end{pmatrix} + \begin{pmatrix} 2 \\ -2 \end{pmatrix} = \begin{pmatrix} 6 \\ 2 \end{pmatrix}$$

Proof (Prop 10.6)

(1) $(\text{add}, +_V)$: Take $\vec{v}, \vec{w}, \vec{u} \in V = \mathbb{R}^n$

$$\text{Then } (\vec{v} + \vec{w}) + \vec{u} \stackrel{\text{Def } +_V}{=} \overrightarrow{(v_1 + w_1, \dots, v_n + w_n) + u}$$

$$\stackrel{\text{Def } +_V}{=} \overrightarrow{((v_1 + w_1) + u_1, \dots, (v_n + w_n) + u_n)}$$

$$\stackrel{\text{Def } +_V}{=} \overrightarrow{v_1 + (w_1 + u_1), \dots, v_n + (w_n + u_n)}$$

$+_{\mathbb{R}}$ is associative

$$\stackrel{\text{Def } +_V}{=} \vec{v} + (w_1 + u_1, \dots, w_n + u_n)$$

$$\stackrel{\text{Def } +_V}{=} \vec{v} + (\vec{w} + \vec{u})$$

(inv, +) Take $\vec{v} \in V = \mathbb{R}^n$

Put $\vec{w} = \overrightarrow{(-v_1, \dots, -v_n)}$.

Then

$$\vec{v} + \vec{w} = \overrightarrow{(v_1 + (-v_1), \dots, v_n + (-v_n))}$$

\uparrow
Def +

$$= \overrightarrow{(0_{\mathbb{R}}, \dots, 0_{\mathbb{R}})} = \vec{0}$$

\uparrow
-1 is the
additive inverse
of 1 in \mathbb{R}

Similar for $\vec{w} + \vec{v}$.

The remaining assertions are left
as an exercise. \square

Remark 108: There is only one additive
inverse for \vec{v} .

Proof: Let \vec{w}, \vec{u} be additive inverses
for \vec{v} . Then

$$\vec{u} = \vec{u} + \vec{0} = \vec{u} + (\vec{v} + \vec{w}) = (\vec{u} + \vec{v}) + \vec{w}$$

\uparrow \uparrow \uparrow
 $(0, +)$ \vec{w} add inv. $(\text{ass}, +)$

$$= \vec{0} + \vec{w} = \vec{w}$$

\uparrow \uparrow
 \vec{u} add inv. $(0, +)$

We write $-\vec{v}$ for the additive
inverse of \vec{v} , i.e. $-\vec{v} = \overrightarrow{(-v_1, \dots, -v_n)}$. \square

Remark 109: 1) The properties in Proposition 106 are called the "vector space properties"

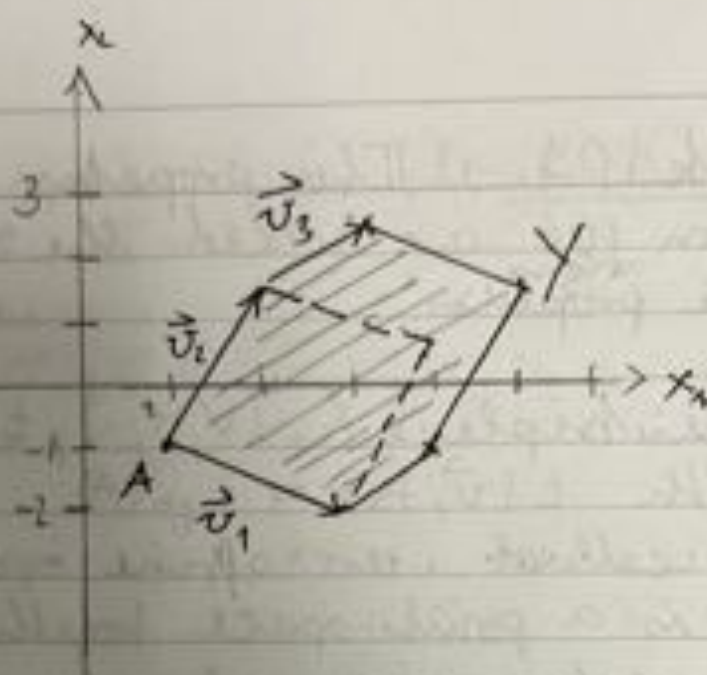
2) The triple $(X, (V, +, \cdot), t: V \times X \rightarrow X)$ with $t(\vec{v}, A) := t_{\vec{v}}(A)$ is called an "affine space". It is a point space together with a vector space where one can translate points along vectors.

Example 110: (a) $A = (1, -1) \in X = \mathbb{R}^2$
 $\vec{v}_1 = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$, $\vec{v}_2 = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$, $\vec{v}_3 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$

$$\text{Put } Y := \left\{ t_{(\lambda_1 \vec{v}_1 + \lambda_2 \vec{v}_2 + \lambda_3 \vec{v}_3)}(A) \mid \lambda_1, \lambda_2, \lambda_3 \in [0, 1] \right\}$$

We draw Y .

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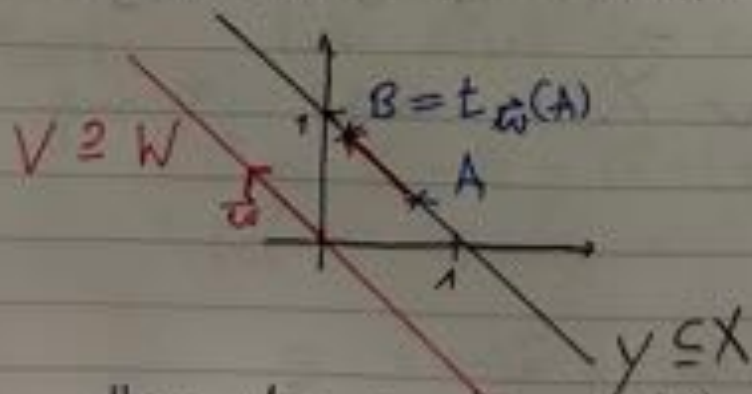
Describe Y using inequalities.

$$\text{I } 8 \geq x_1 + 2x_2 \geq -1$$

$$\text{II } 2.5x_1 - x_2 \geq 3.5$$

$$\text{III } 5 \geq x_1 - x_2 \geq 0.5$$

(b) Consider $(X = \mathbb{R}^2, V = \mathbb{R}^2)$ and the line $Y := \{(x_1, x_2) \in X \mid x_1 + x_2 = 1\}$



How to make Y to an affine space?

Consider $W := \{ \begin{pmatrix} v_1 \\ v_2 \end{pmatrix} \in V \mid v_1 + v_2 = 0 \}$

1st $(W, +|_{W \times W}, \cdot|_{\mathbb{R} \times W})$ is a

vector space, i.e. satisfies the
— " — axioms:

For that we just need to show
that $+$ and \cdot map into W .

$+$: $\vec{w}_1^{(1)}, \vec{w}_2^{(2)} \in W$ To show $\vec{w}_1^{(1)} + \vec{w}_2^{(2)} \in W$

$$\vec{w}_1^{(1)} + \vec{w}_2^{(2)} = \left(\underbrace{w_1^{(1)} + w_1^{(2)}}_{=: u_1}, \underbrace{w_2^{(1)} + w_2^{(2)}}_{=: u_2} \right)$$

and

$$u_1 + u_2 = (w_1^{(1)} + w_1^{(2)}) + (w_2^{(1)} + w_2^{(2)})$$

$$= (w_1^{(1)} + w_2^{(1)}) + (w_1^{(2)} + w_2^{(2)})$$

$$= 0$$

$$\vec{w}_1^{(1)}, \vec{w}_2^{(2)} \in W$$

$$\Rightarrow \vec{u} \in W$$

$\therefore \lambda \in \mathbb{R}, \vec{w} \in W$

$$\lambda \vec{w} = (\lambda w_1, \lambda w_2) \text{ and}$$

$$\lambda w_1 + \lambda w_2 \stackrel{(\text{1 dist})}{=} \lambda (w_1 + w_2) = \lambda \underset{\mathbb{R}}{0} = \underset{\mathbb{R}}{0}$$

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$$\Rightarrow A\vec{w} \in W$$

2nd We also need that $t: W \times Y \rightarrow V$ has its image in V .

$$\vec{w} \in W, A \in Y. \text{ Put } B := t_{\vec{w}}(A)$$

$$\Rightarrow (b_1, b_2) = (a_1 + w_1, a_2 + w_2)$$

$$\text{and } b_1 + b_2 = a_1 + w_1 + a_2 + w_2 = 1$$

$$\Rightarrow B \in Y.$$

(Y, W) is an affine space.

Remark III: For an affine space one needs some more axioms on $t: V \times X \rightarrow X$,

Have an idea what axioms are needed?

$$\text{(aff 1)} \quad t_{\vec{0}}(A) = A \quad \forall A \in X$$

$$\text{(aff 2)} \quad t_{(\vec{v} + \vec{w})}(A) = t_{\vec{v}}(t_{\vec{w}}(A))$$

$$\text{(aff 3)} \quad \forall A, B \in X \exists \vec{v} \in V \quad t_{\vec{v}}(A) = B.$$

III 3 the dot product on \mathbb{R}^n

We need on $V = \mathbb{R}^n$ an extra structure to be able to

- compute the length of a vector and
- the angle between two non-zero vectors.

Def 112: (dot product)

The dot product is the map

$$\bullet: V \times V \xrightarrow{\text{Text}} \mathbb{R}$$

defined via $\vec{v} \bullet \vec{w} := \sum_{i=1}^n v_i w_i$

$$=: (v_1, \dots, v_n) \circ \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix} \text{ (using matrix multiplication)}$$

" \bullet " is also called the Euclidean inner product.

Example 113:

$$(a) \quad \vec{v} = (1, -1, \frac{1}{2}, 3, 5) \in V = \mathbb{R}^5$$

$$\vec{w} = (0, 2, 7, 13, 1) \in V$$

$$\vec{v} \bullet \vec{w} = 1 \cdot 0 + (-1) \cdot 2 + \frac{1}{2} \cdot 7 + 3 \cdot 13 + 5 \cdot 1$$

$$= -2 + 3.5 + 39 + 5 = \cancel{45} 45.5$$

End of Lecture 1st of Nov. 2022.

(b) The dot product can be used to describe $\|\cdot\|$.

$$\|\vec{v}\| = |\vec{v} \cdot \vec{v}|^{\frac{1}{2}}$$

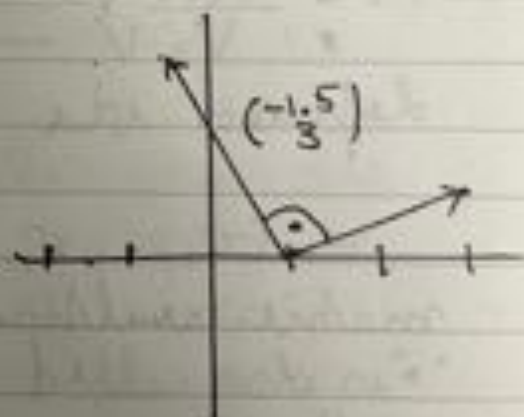
Ex. g.: For \vec{v} in (a):

$$\|\vec{v}\| = |\vec{v} \cdot \vec{v}|^{\frac{1}{2}} = \sqrt{1+1+\frac{1}{4}+9+25}$$

$$= \sqrt{36.25}$$

(c) $\begin{pmatrix} 2 \\ 1 \end{pmatrix}, \begin{pmatrix} -1.5 \\ 3 \end{pmatrix} \in V = \mathbb{R}^2$

$$\begin{pmatrix} 2 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} -1.5 \\ 3 \end{pmatrix} = 2(-1.5) + 1 \cdot 3 = 0$$



Def 114: (orthogonal vectors)

Two vectors $\vec{v}, \vec{w} \in V \setminus \{0\}$ are called orthogonal (or perpendicular) if $\vec{v} \cdot \vec{w} = 0$.

Def 115: A vector of norm 1 is called a unit vector.

Ex: (a) $\left\| \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right\| = \sqrt{1^2 + 0^2} = 1$

$\begin{pmatrix} 1 \\ 0 \end{pmatrix}$ is a unit vector

(b) $\left\| \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix} \right\| = \sqrt{4 + 9 + 1} = \sqrt{14}$

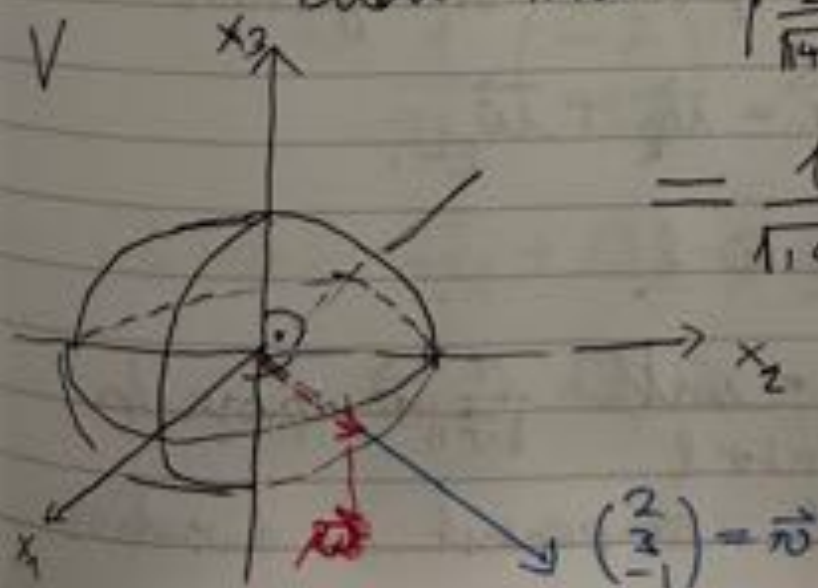
$\vec{v} = \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix}$ is not a unit vector

We can "normalize" the vector \vec{v} .

$$\vec{v}_{\text{norm}} := \vec{w} := \frac{1}{\|\vec{v}\|} \cdot \vec{v} = \frac{1}{\sqrt{14}} \begin{pmatrix} 2 \\ 3 \\ -1 \end{pmatrix} = \begin{pmatrix} \frac{2}{\sqrt{14}} \\ \frac{3}{\sqrt{14}} \\ -\frac{1}{\sqrt{14}} \end{pmatrix}$$

Then $\|\vec{w}\| = \sqrt{\frac{2^2}{14^2} + \frac{3^2}{14^2} + \frac{1^2}{14^2}}$

$$= \frac{1}{\sqrt{14}} \|\vec{v}\| = \frac{\sqrt{14}}{\sqrt{14}} = 1.$$

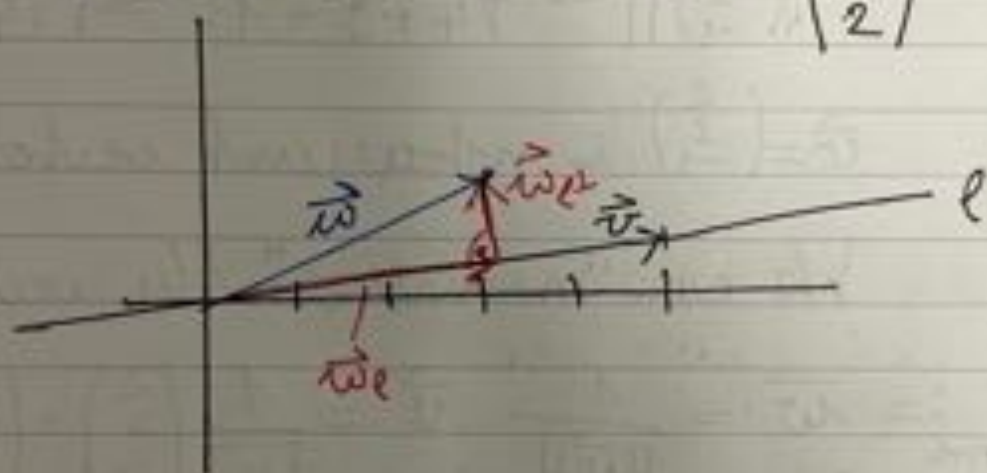


\vec{w} lies on the unit sphere.

Remark 116: (geometric interpretation of the dot product)

Consider the line $l \subseteq V = \mathbb{R}^2$
through $\vec{v} = \begin{pmatrix} 5 \\ 1 \end{pmatrix}$

and a vector $\vec{w} = \begin{pmatrix} 3 \\ 2 \end{pmatrix}$



We want to write \vec{w} as
the sum of two orthogonal
vectors

$$\vec{w} = \vec{w}_{\parallel} + \vec{w}_{\perp}$$

such $\vec{w}_{\parallel} \in l$.

Idea: The \bullet with $\frac{1}{\|\vec{v}\|} \vec{v}$ projects
 \vec{w} onto l

$\vec{w} \cdot \vec{v}_{\text{norm}}$ is the component in direction
of \vec{v}_{norm} .

$$\vec{w}_e := \left(\vec{w} \cdot \frac{\vec{v}}{\|\vec{v}\|} \right) \frac{\vec{v}}{\|\vec{v}\|} \in \ell$$

$$= \left(\begin{pmatrix} 3 \\ 2 \end{pmatrix} \cdot \begin{pmatrix} 5 \cdot \frac{1}{\sqrt{26}} \\ \frac{1}{\sqrt{26}} \end{pmatrix} \right) \cdot \begin{pmatrix} 5/\sqrt{26} \\ 1/\sqrt{26} \end{pmatrix}$$

$$= \left(\frac{1}{\sqrt{26}} \cdot 15 + \frac{1}{\sqrt{26}} \cdot 2 \right) \begin{pmatrix} 5 \\ 1 \end{pmatrix} \cdot \frac{1}{\sqrt{26}}$$

$$= \frac{17}{26} \begin{pmatrix} 5 \\ 1 \end{pmatrix} = \begin{pmatrix} 85/26 \\ 17/26 \end{pmatrix}$$

$$\vec{w}_{e\perp} := \vec{w} - \vec{w}_e$$

$$= \begin{pmatrix} 3 \\ 2 \end{pmatrix} - \frac{17}{26} \begin{pmatrix} 5 \\ 1 \end{pmatrix}$$

$$= \frac{1}{26} \begin{pmatrix} -7 \\ 35 \end{pmatrix}$$

$$\text{Check: } \vec{w}_e + \vec{w}_{e\perp} = \vec{w} \quad \checkmark$$

$$\vec{w}_e \cdot \vec{w}_{e\perp} = \frac{17}{26^2} (5(-7) + 1 \cdot 35)$$

$$= \frac{17}{26^2} \cdot 0 = 0 \quad \checkmark$$

This works in general if $\vec{v} \neq \vec{0}$

Prop 117
Let $\vec{w}, \vec{v} \in V = \mathbb{R}^n$. $L = \mathbb{R}\vec{v} \subseteq V$.

$$\text{Put } \vec{u} = \vec{v}_{\text{norm}} := \frac{1}{\|\vec{v}\|} \vec{v}.$$

$$\text{Then (a) } \vec{w} = \vec{w}_L + \vec{w}_{L^\perp}$$

for some $\vec{w}_L \in L$ and $\vec{w}_{L^\perp} \in V$
orthogonal to \vec{w}_L .

(b) The decomposition in (a)
is unique. In fact we
have

$$\vec{w}_L = (\vec{w} \cdot \vec{u}) \vec{u} \text{ and}$$

$$\vec{w}_{L^\perp} = \vec{w} - \vec{w}_L$$

Proof: Exercise in example class. \square

Example 118: ($n=4$) $\vec{w} = (1, -1, 2, 1)$
 $\vec{v} = (\frac{3}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}, 0)$

$$\Rightarrow \|\vec{v}\| = 1, \text{ i.e. } \vec{v}_{\text{norm}} = \vec{v}$$

$$\vec{w} = \vec{w}_{\vec{v}} + \vec{w}_{\vec{v}^\perp} \text{ with}$$

$$\begin{aligned} \vec{w}_{\vec{v}} &= (\vec{w} \cdot \vec{v}) \vec{v} = \frac{3}{\sqrt{2}} \left(\frac{1}{\sqrt{2}}, 0, \frac{1}{\sqrt{2}}, 0 \right) \\ &= \left(\frac{3}{2}, 0, \frac{3}{2}, 0 \right) \end{aligned}$$

and $\vec{w}_{\vec{v} \perp} = \vec{w} - \vec{w}_{\vec{v}} = (-\frac{1}{2}, -1, \frac{1}{2}, 1)$.

Prop 119: (Properties of the dot product)

The dot product is

(a) bilinear, i.e. for all $\lambda \in \mathbb{R}$
and $\vec{w}, \vec{v}^{(1)}, \vec{v}^{(2)} \in V$ we have

(bi-additivity)

$$(\vec{v}^{(1)} + \vec{v}^{(2)}) \cdot \vec{w} = \vec{v}^{(1)} \cdot \vec{w} + \vec{v}^{(2)} \cdot \vec{w}$$

$$\vec{w} \cdot (\vec{v}^{(1)} + \vec{v}^{(2)}) = \vec{w} \cdot \vec{v}^{(1)} + \vec{w} \cdot \vec{v}^{(2)}$$

(bi-homogeneous property)

$$(\lambda \vec{v}) \cdot \vec{w} = \lambda (\vec{v} \cdot \vec{w})$$

$$\vec{v} \cdot (\lambda \vec{w}) = \lambda (\vec{v} \cdot \vec{w})$$

(b) symmetric: $\forall \vec{v}, \vec{w} \in V$:
 $\vec{v} \cdot \vec{w} = \vec{w} \cdot \vec{v}$

(c) positive definite: $\forall \vec{v} \in V$:
 $\vec{v} \cdot \vec{v} \geq 0$

and

$$(\vec{v} \cdot \vec{v} = 0 \iff \vec{v} = 0)$$

Proof: (a) Follows from the properties of matrix multiplication as

$$\vec{v} \cdot \vec{w} = (v_1, \dots, v_n) \cdot \begin{pmatrix} w_1 \\ \vdots \\ w_n \end{pmatrix}$$

$$\begin{aligned}
 (b) \quad \vec{v} \cdot \vec{w} &= v_1 w_1 + \dots + v_n w_n \\
 &= w_1 v_1 + \dots + w_n v_n \\
 &\stackrel{\substack{\uparrow \\ \mathbb{R} \text{ commutative}}}{=} \\
 &= \vec{w} \cdot \vec{v}
 \end{aligned}$$

$$(c) \quad 1) \quad \vec{v} \cdot \vec{v} = \sum_{i=1}^n v_i^2 \geq 0$$

$$2) \quad \vec{0} \cdot \vec{0} = \sum_{i=1}^n 0^2 = 0$$

3) Suppose $\vec{v} \cdot \vec{v} = 0$. Then

$$\sum_{i=1}^n v_i^2 = 0 \quad \text{Assume } \exists i_0 \text{ s.t. } v_{i_0} > 0$$

$$\text{Then } \vec{v} \cdot \vec{v} \geq v_{i_0}^2 > 0 \quad \nexists$$

$$\text{Thus } \vec{v} = \vec{0}.$$

□

$$\begin{aligned}
 (b) \quad \vec{v} \cdot \vec{w} &= v_1 w_1 + \dots + v_n w_n \\
 &\stackrel{\substack{\uparrow \\ \mathbb{R} \text{ commutative}}}{=} w_1 v_1 + \dots + w_n v_n \\
 &= \vec{w} \cdot \vec{v}
 \end{aligned}$$

$$(c) \quad 1) \quad \vec{v} \cdot \vec{v} = \sum_{i=1}^n v_i^2 \geq 0$$

$$2) \quad \vec{0} \cdot \vec{0} = \sum_{i=1}^n 0^2 = 0$$

3) Suppose $\vec{v} \cdot \vec{v} = 0$. Then

$$\sum_{i=1}^n v_i^2 = 0 \quad \text{Assume } \exists_{i_0} \begin{cases} v_{i_0} > 0 \\ v_{i_0} < 0 \end{cases}$$

$$\text{Then } \vec{v} \cdot \vec{v} \geq v_{i_0}^2 > 0 \quad \nabla$$

$$\text{Thus } \vec{v} = \vec{0}.$$

Example 120 (*) in $V = \mathbb{R}^3$ □

$$\begin{aligned}
 &((0, 1, -1) + (1, 2, 3)) \cdot (7, 0, 9) = (1, 3, 2) \\
 &\qquad \qquad \qquad \qquad \qquad \qquad \qquad \qquad \cdot (7, 0, 9)
 \end{aligned}$$

$$= 7 \cdot 1 + 3 \cdot 0 + 2 \cdot 9 = 7 + 18 = 25$$

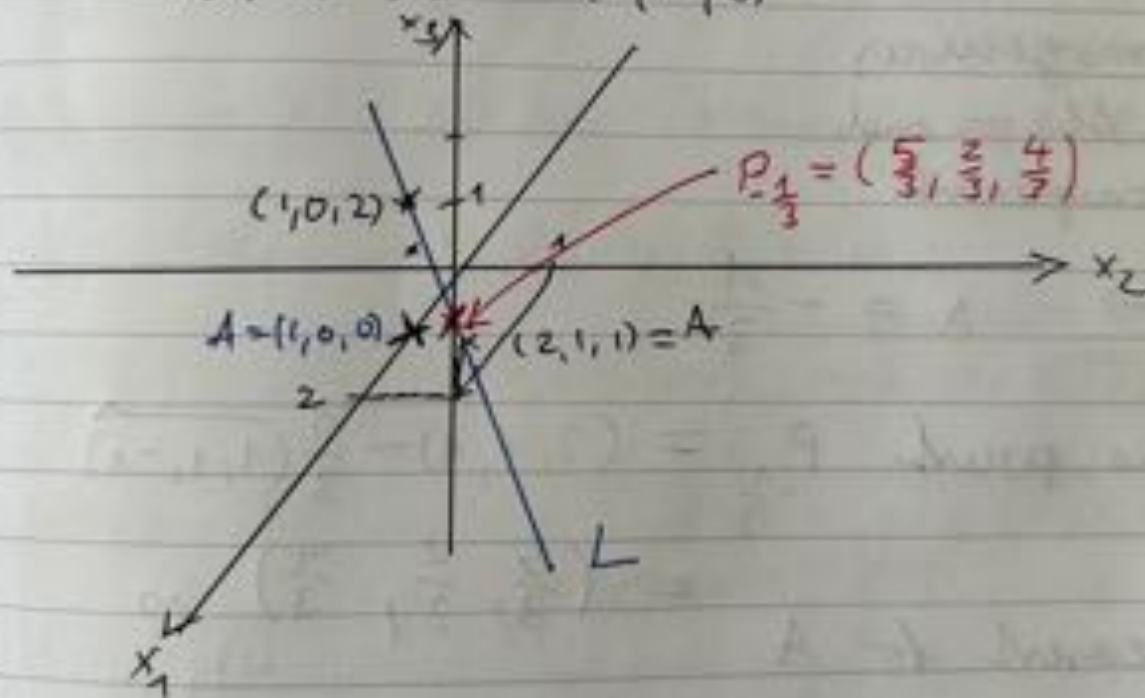
$$\begin{aligned}
 &(0, 1, -1) \cdot (7, 0, 9) + (1, 2, 3) \cdot (7, 0, 9) \\
 &= -9 + (7 + 27) = 25
 \end{aligned}$$

(b) We consider the following line in $X = \mathbb{R}^3$

$$L := (2, 1, 1) + \mathbb{R} \overrightarrow{(1, 1, -1)} \subseteq X$$

"we also write +
for $t \overrightarrow{(2, 1, 1)}$
 $\overrightarrow{(1, 1, -1)}$ "

Take $A = (1, 0, 0)$



Which point on L is nearest to A ?
I.e. for which $\lambda \in \mathbb{R}$ we have

$$\overrightarrow{(1, 1, -1)} \perp \overrightarrow{A P_\lambda} \quad P_\lambda = (2, 1, 1) + \lambda \overrightarrow{(1, 1, -1)}$$

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$$Q = P_0 = (2, 1, 1)$$

$$0 = \overrightarrow{(1, 1, -1)} \cdot \overrightarrow{AP_\lambda} \stackrel{\downarrow}{=} \overrightarrow{(1, 1, -1)} \cdot (\overrightarrow{AQ} + \overrightarrow{QP_\lambda})$$

$$= \overrightarrow{(1, 1, -1)} \cdot \overrightarrow{AQ} + \overrightarrow{(1, 1, -1)} \cdot \overrightarrow{QP_\lambda}$$

biadditivity

$$= \overrightarrow{(1, 1, -1)} \cdot \overrightarrow{(1, 1, 1)} + \overrightarrow{(1, 1, -1)} \cdot (\lambda \overrightarrow{(1, 1, -1)})$$

$$= 1 + \lambda \overrightarrow{(1, 1, -1)} \cdot \overrightarrow{(1, 1, -1)} = 1 + \lambda \cdot 3$$

homogeneous
on the second
component

$$\Leftrightarrow \lambda = -\frac{1}{3}$$

The point $P_{-\frac{1}{3}} = (2, 1, 1) - \frac{1}{3} \overrightarrow{(1, 1, -1)}$

$$= \left(\frac{5}{3}, \frac{2}{3}, \frac{4}{3}\right) \text{ is}$$

nearest to A.

Def 121: (i) The distance (Euclidean distance) between points $P, Q \in X = \mathbb{R}^n$ is defined via

$$d(P, Q) := \|\overrightarrow{PQ}\| = \sqrt{\sum_{i=1}^n (P_i - Q_i)^2}$$

(ii) Let $Y \subseteq X$ and $A \in X$. The distance between A and Y is defined via

$$\text{dist}(A, Y) := \inf \{d(A, P) \mid P \in Y\}$$

$$= \inf_{P \in Y} d(A, P)$$

(iii) $Y_1, Y_2 \subseteq X$ non-empty. $\text{dist}(Y_1, Y_2) = \inf_{P \in Y_1, Q \in Y_2} d(P, Q)$

Example 122: (i) In Example 120 (b)

we have $d(A, P_\lambda)$

$$= \|\overrightarrow{AP_\lambda}\| = \|(1+\lambda, 1+\lambda, 1-\lambda)\|,$$

$$\left(\text{as } \overrightarrow{AP_\lambda} = \overrightarrow{(1, 0, 0) - (2+\lambda, 1+\lambda, 1-\lambda)} \right)$$

$$= \overrightarrow{(1+\lambda, 1+\lambda, 1-\lambda)}$$

$$= \sqrt{(1+\lambda)^2 + (1+\lambda)^2 + (1-\lambda)^2}$$

$$= \sqrt{3 + 2\lambda + 3\lambda^2}$$

$$\text{and } d(A, P_{\frac{1}{3}}) = \sqrt{3 - \frac{2}{3} + \frac{1}{3}} = 2\sqrt{\frac{2}{3}}$$

Check! $\sqrt{\frac{8}{3}} \leq \sqrt{3 + 2\lambda + 3\lambda^2}$

$$\begin{aligned} (3 + 2\lambda + 3\lambda^2 &= 3(\lambda^2 + 2 \cdot \frac{1}{3}\lambda + 1) \\ &= 3\left(\left(\lambda + \frac{1}{3}\right)^2 + \frac{8}{9}\right) \geq 3 \cdot \frac{8}{9} = \frac{8}{3}) \end{aligned}$$

Thus $2\sqrt{\frac{2}{3}} = \text{dist}(A, L)$

(ii) Consider $T, S \subseteq X = \mathbb{R}^2$ defined via

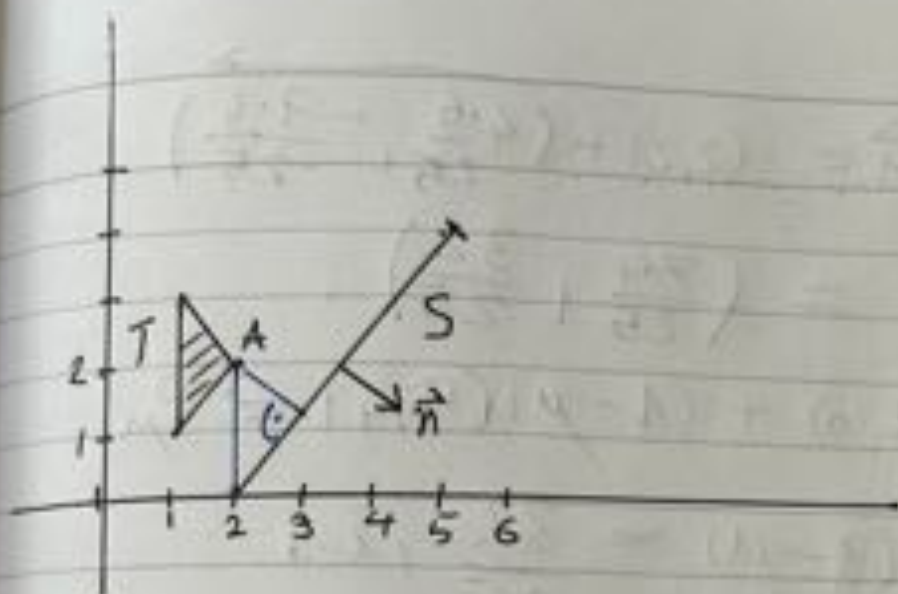
$$T = \left[\lambda_1(1, 1) + \lambda_2(1, 3) + \lambda_3(2, 2) \right]$$

$$\left. \begin{aligned} 0 \leq \lambda_i \leq 1, \quad i=1, 2, 3, \text{ and} \\ \lambda_1 + \lambda_2 + \lambda_3 = 1 \end{aligned} \right\}$$

$$S = \left\{ \mu(2, 0) + (1-\mu)(5, 4) \mid 0 \leq \mu \leq 1 \right\}$$

$$= \left\{ (5, 4) + \mu(-3, -4) \mid 0 \leq \mu \leq 1 \right\}$$

Compute $\text{dist}(T, S)$.



(Note: The lower edge of T and S are not "parallel.")

Guess: $A := (2, 2)$ is closest to S.

The distance of A to the line L through S is

$$\text{dist}(A, L) = \left| \overrightarrow{QA} \cdot \vec{n} \right| \quad \text{with } Q = (2, 0) \\ \text{and } \vec{n} = \frac{1}{\sqrt{25}} (4, -3)$$

$$= \left| \overrightarrow{(2, 0)(2, 2)} \cdot \frac{1}{5} \overrightarrow{(4, -3)} \right|$$

$$= \frac{1}{5} \left| \overrightarrow{(0, 2)} \cdot \overrightarrow{(4, -3)} \right| = \frac{1}{5} 6.$$

The orthogonal projection of A to L (along \vec{n}) is

$$A + \frac{6}{5} \vec{n} = (2, 2) + \left(\frac{4 \cdot 6}{25}, -\frac{3 \cdot 6}{25} \right)$$

$$= \left(\frac{74}{25}, \frac{32}{25} \right)$$

$$= \mu(2, 0) + (1 - \mu)(5, 4) =: P_\mu$$

for $4(1 - \mu) = \frac{32}{25}$ i.e.

$$\mu = 1 - \frac{8}{25} = \frac{17}{25} \in [0, 1].$$

Thus $P_\mu \in S$.

We need to prove the given.
(Exercise!)

Hint: $(2, 0) = \lambda_1(1, 1) + \lambda_2(1, 3) + \lambda_3(2, 2)$

$$= (\lambda_1(1, 1) + \lambda_2(1, 3) + \lambda_3(2, 2)) - (2, 0)$$

$$= \lambda_1((1, 1) - (2, 0)) + \lambda_2((1, 3) - (2, 0)) + \lambda_3((2, 2) - (2, 0))$$

$$\uparrow$$

$$\lambda_1 + \lambda_2 + \lambda_3 = 1$$

$$= \lambda_1(-1, 1) + \lambda_2(-1, 3) + \lambda_3(0, 2)$$

$$\neq \vec{v} \text{ or } \vec{v}$$

$$\text{and } \overrightarrow{(-1,1)} \cdot (-\vec{n}) = \overrightarrow{(-1,1)} \cdot \frac{1}{5} \overrightarrow{(-4,3)} = \frac{7}{5} > \frac{6}{5}$$

$$\overrightarrow{(-1,3)} \cdot (-\vec{n}) = \overrightarrow{(-1,3)} \cdot \frac{1}{5} \overrightarrow{(-4,3)} = \frac{13}{5} > \frac{6}{5}$$

End of Lecture 3rd of Nov 23.

Theorem 12.3: (Norm properties)

$\|\cdot\|: V \rightarrow \mathbb{R}^{\geq 0}$ defined via $\|\vec{v}\| := \left(\sum_{i=1}^n v_i^2\right)^{\frac{1}{2}}$ satisfies the following norm axioms:

(N1) $\forall \vec{v} \in V: \|\vec{v}\| = 0 \Leftrightarrow \vec{v} = \vec{0}$.

(" $\|\cdot\|$ is definite")

(N2) $\forall \vec{v} \in V \forall \lambda \in \mathbb{R}:$

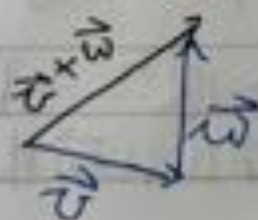
$$\|\lambda \vec{v}\| = |\lambda| \|\vec{v}\|$$

(" $\|\cdot\|$ is absolute homogeneous")

(N3) $\forall \vec{v}, \vec{w} \in V:$

$$\|\vec{v} + \vec{w}\| \leq \|\vec{v}\| + \|\vec{w}\|.$$

("triangle inequality")



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Example 124: ($n=4$)

$$A = (0, 1, 0, 1), \quad B = (1, -1, 0, 1), \quad C = (2, 0, 1, 1)$$



$$d(A, B) = \|(1, -2, 0, 0)\| = \sqrt{5}$$

$$d(B, C) = \|(1, 1, 1, 0)\| = \sqrt{3}$$

$$d(A, C) = \|(2, -1, 1, 0)\| = \sqrt{6}$$

We have $\sqrt{5} + \sqrt{3} \stackrel{(*)}{\geq} \sqrt{6}$

Proof:

$$(*) \Leftrightarrow 8 + 2\sqrt{15} \geq 6$$

$$\Leftrightarrow \sqrt{15} \geq -1 \quad \checkmark$$

~~8 + 2\sqrt{15} \geq 6~~ \square

So we have

$$d(A, B) + d(B, C) \geq d(A, C)$$

Lemma 125 (Cauchy-Schwartz inequality)

Let $\vec{v}, \vec{w} \in V = \mathbb{R}^n$. Then

$$|\vec{v} \cdot \vec{w}| \leq \|\vec{v}\| \|\vec{w}\|.$$

Proof - At first we have

$$ab \leq |a| |b| \leq \frac{1}{2} a^2 + \frac{1}{2} b^2$$

for all $a, b \in \mathbb{R}$.

$$\begin{aligned} (0 \leq (|a| - |b|)^2 &= a^2 + b^2 - 2|a||b| \\ \Rightarrow |a||b| &\leq \frac{1}{2} a^2 + \frac{1}{2} b^2) \end{aligned}$$

Take $\vec{v}, \vec{w} \in V$. Then in case of $\vec{v} = \vec{0}$ or $\vec{w} = \vec{0}$, we get

$$0 = |\vec{v} \cdot \vec{w}| \leq 0 = \|\vec{v}\| \|\vec{w}\|$$

and if $\vec{v}, \vec{w} \in V \setminus \{\vec{0}\}$ we get

$$\frac{v_i}{\|\vec{v}\|} \cdot \frac{w_i}{\|\vec{w}\|} \leq \frac{1}{2} \frac{v_i^2}{\|\vec{v}\|^2} + \frac{1}{2} \frac{w_i^2}{\|\vec{w}\|^2}$$

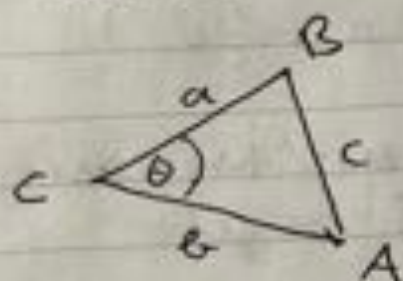
$$\Rightarrow \sum_1^1 (\vec{v} \cdot \vec{w}) \cdot \frac{1}{\|\vec{v}\|} \cdot \frac{1}{\|\vec{w}\|} \leq \frac{1}{2} + \frac{1}{2} \leq 1$$

$$\Rightarrow (\vec{v} \cdot \vec{w}) \leq \|\vec{v}\| \|\vec{w}\|$$

Same for $-\vec{v}$, or $-(\vec{v} \cdot \vec{w}) \leq \|\vec{v}\| \|\vec{w}\|$. \square

Remark 126: (geometric meaning of the Cauchy - Schwarz inequality)

We want to define angles using the cosine law.



Put $\vec{v} := \overrightarrow{CB}$ and $\vec{w} := \overrightarrow{CA}$.
We want $\theta \in [0, \pi]$ to satisfy

$$c^2 = a^2 + b^2 - 2ab \cos(\theta).$$

$$\Leftrightarrow \|\vec{v} + \vec{w}\|^2 = \|\vec{v}\|^2 + \|\vec{w}\|^2 - 2\|\vec{v}\|\|\vec{w}\|\cos(\theta) \quad (*)$$

$$\begin{aligned} \text{We have } \|\vec{v} + \vec{w}\|^2 &= (\vec{v} + \vec{w}) \cdot (\vec{v} + \vec{w}) \\ &= \vec{v} \cdot \vec{v} + 2\vec{v} \cdot \vec{w} + \vec{w} \cdot \vec{w} \\ &= \|\vec{v}\|^2 + 2\vec{v} \cdot \vec{w} + \|\vec{w}\|^2 \end{aligned}$$

$$\text{Thus } (*) \Leftrightarrow \vec{v} \cdot \vec{w} = \|\vec{v}\|\|\vec{w}\|\cos(\theta)$$



a, b non-zero

$$\cos \theta = \frac{\vec{v} \cdot \vec{w}}{\|\vec{v}\| \|\vec{w}\|}$$

So to define θ we need

$$-1 \leq \frac{\vec{v} \cdot \vec{w}}{\|\vec{v}\| \|\vec{w}\|} \leq 1$$

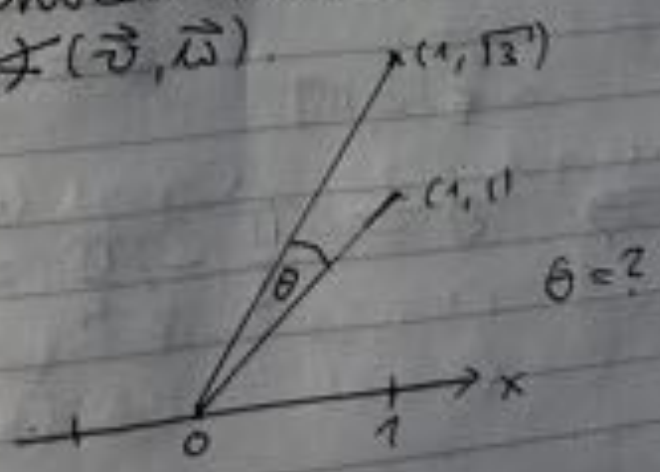
This is provided by the Cauchy-Schwarz inequality.

Def 12.7: Let $\vec{v}, \vec{w} \in V = \mathbb{R}^n$ non-zero. The number $\theta \in [0, \pi]$ satisfying

$$\cos \theta = \frac{\vec{v} \cdot \vec{w}}{\|\vec{v}\| \|\vec{w}\|}$$
 is called

the angle between \vec{v} and \vec{w} . We write $\angle(\vec{v}, \vec{w})$.

Example 12.8:



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$$\cos(\theta) = \frac{\begin{pmatrix} 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ \sqrt{3} \end{pmatrix}}{\sqrt{2} \cdot \sqrt{4}} = \frac{1 + \sqrt{3}}{\sqrt{2} \cdot 2}$$

$$\theta = ?$$

Another way: $\theta = \beta - \alpha$ with

$$\beta := \angle \left(\begin{pmatrix} 1 \\ \sqrt{3} \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right)$$

$$\alpha := \angle \left(\begin{pmatrix} 1 \\ 1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \end{pmatrix} \right)$$

$$\cos \beta = \frac{\begin{pmatrix} 1 \\ \sqrt{3} \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}}{\sqrt{4} \cdot \sqrt{1}} = \frac{1}{2}$$

$$\begin{array}{l} \Rightarrow \\ \uparrow \\ \beta \in [0, \pi] \end{array} \quad \beta = \frac{\pi}{3}$$

$$\cos \alpha = \frac{\begin{pmatrix} 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}}{\sqrt{2} \cdot \sqrt{1}} = \frac{1}{\sqrt{2}}$$

$$\begin{array}{l} \Rightarrow \\ \alpha \in [0, \pi] \end{array} \quad \alpha = \frac{\pi}{4}$$

$$\Rightarrow \theta = \frac{\pi}{3} - \frac{\pi}{4} = \frac{\pi}{12}$$

Proof of Theorem 12.3:

(definite) $\cdot \|\vec{0}\| = \|(0, \dots, 0)\|$
 $= \sqrt{0^2 + \dots + 0^2} = 0$

\cdot If $\|\vec{v}\| = 0$ and $\exists i \in \{1, \dots, n\}$:
 $v_i \neq 0$ then

$$0 = \|\vec{v}\|^2 = v_1^2 + \dots + v_n^2 \geq v_i^2 > 0$$

(absolute homogeneous)

$$\|\lambda \vec{v}\| = \|(\lambda v_1, \dots, \lambda v_n)\|$$

$$= \left(\sum_{i=1}^n \lambda^2 v_i^2 \right)^{\frac{1}{2}}$$

$$= |\lambda| \left(\sum_{i=1}^n v_i^2 \right)^{\frac{1}{2}} = |\lambda| \|\vec{v}\|$$

$$|\lambda| \geq 0$$

(Δ -inequality)

$$\|\vec{v} + \vec{w}\|^2 = \|\vec{v}\|^2 + 2\vec{v} \cdot \vec{w} + \|\vec{w}\|^2$$

$$\leq \|\vec{v}\|^2 + 2\|\vec{v}\|\|\vec{w}\| + \|\vec{w}\|^2$$

Cauchy-Schwarz
 inequality

$$= (\|\vec{v}\| + \|\vec{w}\|)^2 \quad \square$$

Take $\sqrt{\quad}$

Corollary 129: (metric axioms)

The distance map $d: X \times X \rightarrow \mathbb{R}^{\geq 0}$ satisfies the metric axioms, i.e.

(D1) (being definite)

$$d(P, Q) = 0 \Leftrightarrow P = Q$$

(D2) (symmetry)

$$d(P, Q) = d(Q, P)$$

(D3) (Δ -inequality)

$$d(P, R) \leq d(P, Q) + d(Q, R)$$

Proof: (Exercise) □

Convention 130:

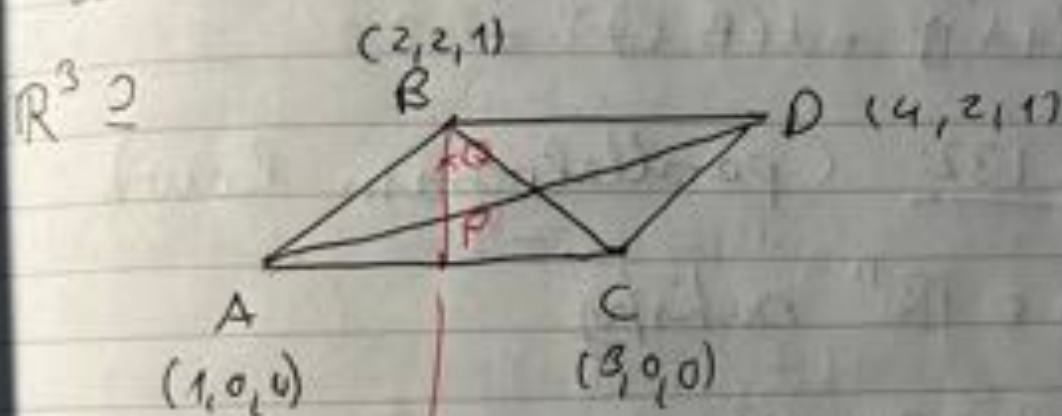
From now on we only work in $V = \mathbb{R}^n$, because we can identify $P \in X = \mathbb{R}^n$ with the vector $\vec{OP} \in V$.

Example 131: Consider the points

$$A = (1, 0, 0), \quad B = (2, 2, 1),$$

$$C = (3, 0, 0), \quad D = (4, 2, 1)$$

"affine combination of points"

The set $Y := \{ \lambda_1 A + \lambda_2 B + \lambda_3 C + \lambda_4 D \mid$ $0 \leq \lambda_i \leq 1 \}$ is a parallelogrambecause $\vec{AC} = \vec{BD}$ and $\vec{AB} = \vec{CD}$ 

$$\frac{1}{2}A + \frac{1}{2}C = (2, 0, 0) = P$$

$$Q = \frac{2}{3}B + \frac{1}{3}P = \frac{2}{3}(2, 2, 1) + \frac{1}{3}(2, 0, 0)$$

$$= \left(\frac{4}{3} + \frac{2}{3}, \frac{4}{3} + 0, \frac{2}{3} + 0 \right) = \left(2, \frac{4}{3}, \frac{2}{3} \right)$$

Relationship between diagonals and edges of the parallelogram.

length of edges

$$d(A, B) = \sqrt{6} = d(C, D)$$

$$d(B, D) = 2 = d(A, C)$$

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length of diagonals

$$d(A, D) = \sqrt{14}$$

$$d(B, C) = \sqrt{6}$$

We have

$$2 d(A, B)^2 + 2 d(A, C)^2 = 20$$

$$d(A, D)^2 + d(B, C)^2 = 20$$

Theorem 132: (parallelogram law)

$v, w \in \mathbb{R}^n$ satisfy

$$2 \|v\|^2 + 2 \|w\|^2 = \|v+w\|^2 + \|v-w\|^2$$

Proof: $\|v+w\|^2 = (v+w) \cdot (v+w)$
 $= \|v\|^2 + \|w\|^2 + 2v \cdot w$

$$\|v-w\|^2 = (v-w) \cdot (v-w)$$

$$= \|v\|^2 + \|w\|^2 - 2v \cdot w$$

add \Rightarrow assertion \square

Note: The parallelogram law uses the dot product in its proof, but the dot product is not in the statement.

Reason: One can prove that the parallelogram law implies the existence of an Euclidean inner product inducing $\|\cdot\|$ via the following identity.

Prop 133: (Relationship: dot product \leftrightarrow inner product)

We have, for $v, w \in \mathbb{R}^n$,

$$v \cdot w = \frac{1}{4} (\|v+w\|^2 - \|v-w\|^2)$$

Proof: exercise. \square

Example 134: $v = (1, 0, 0, 2)$
 $w = (-1, -2, 3, 1)$

$$v \cdot w = 1$$

$$\frac{1}{4} (\|v+w\|^2 - \|v-w\|^2)$$

$$= \frac{1}{4} (\|(0, -2, 3, 3)\|^2 - \|(2, 2, -3, 1)\|^2)$$

$$= \frac{1}{4} (22 - 18) = 1.$$

Example 135: (ISBN numbers)

ISBN $\hat{=}$ international standard
book number

(13 digits)

The last digit is the check
digit.

$d_1 d_2 d_3 - d_4 - d_5 d_6 d_7 d_8 - d_9 d_{10} d_{11} d_{12} - d_{13}$

Write $d = (d_1, \dots, d_{13})$

The ISBN number has to
verify

$$10 \mid d \cdot (1, 3, 1, 3, 1, 3, \dots, 1, 3, 1)$$

Example: 978-7-5327-7274-

$$9 \cdot 1 + 7 \cdot 3 + 8 \cdot 1 + 7 \cdot 3 + 5 \cdot 1 + 3 \cdot 3 + 2 \cdot 1 + 7 \cdot 3 + 7 \cdot 1 + 2 \cdot 3 + 7 \cdot 1 + 4 \cdot 3 + d_{\text{check}} \cdot 1$$

$$\equiv_{10} (-1) \cdot 1 + 1 + (-2) + 1 + 5 + (-1) + 2 + 1 + (-3) + (-4) + (-3) + 2 + d_{\text{check}}$$

equal up to d multiple of 10 ("modulo 10")

$$\equiv_{10} -2 + d_{\text{check}} \equiv_{10} 0$$

$$\Rightarrow d_{\text{check}} \equiv_{10} 2, \text{ i.e.}$$

$$d_{\text{check}} \in \{2 + 10 \cdot k \mid k \in \mathbb{Z}\}$$

$$\begin{matrix} \Rightarrow \\ \uparrow \\ 0 \leq d_{\text{check}} \leq 9 \end{matrix} \quad d_{\text{check}} = 2$$

III 4. Orthogonality

Recall: 1) $v \perp w$ if $v \cdot w = 0$,
 $v, w \in \mathbb{R}^n$.

2) $v \in \mathbb{R}^n \setminus \{0\}$, $w \in \mathbb{R}^n$.

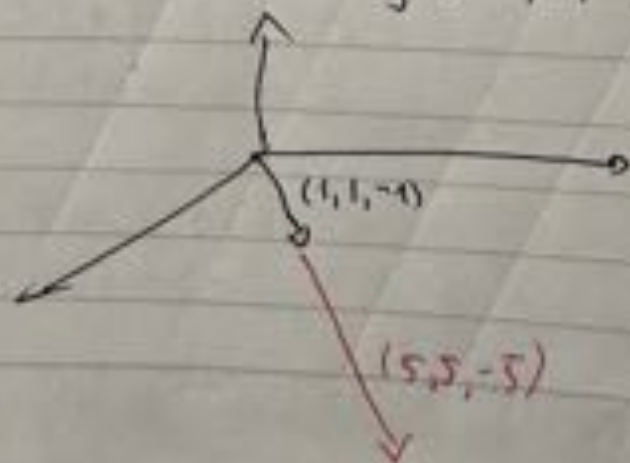
w is called collinear to v if
 $\exists \lambda \in \mathbb{R} \quad w = \lambda v$.

(we also say w is parallel to v)
 Write $w \parallel v$

Example 136:

(a) $(1, 1, -1)$ is collinear to
 $(5, 5, -5)$, because

$$(1, 1, -1) = \frac{1}{5}(5, 5, -5)$$



(b) $\vec{0}$ is collinear to every vector.

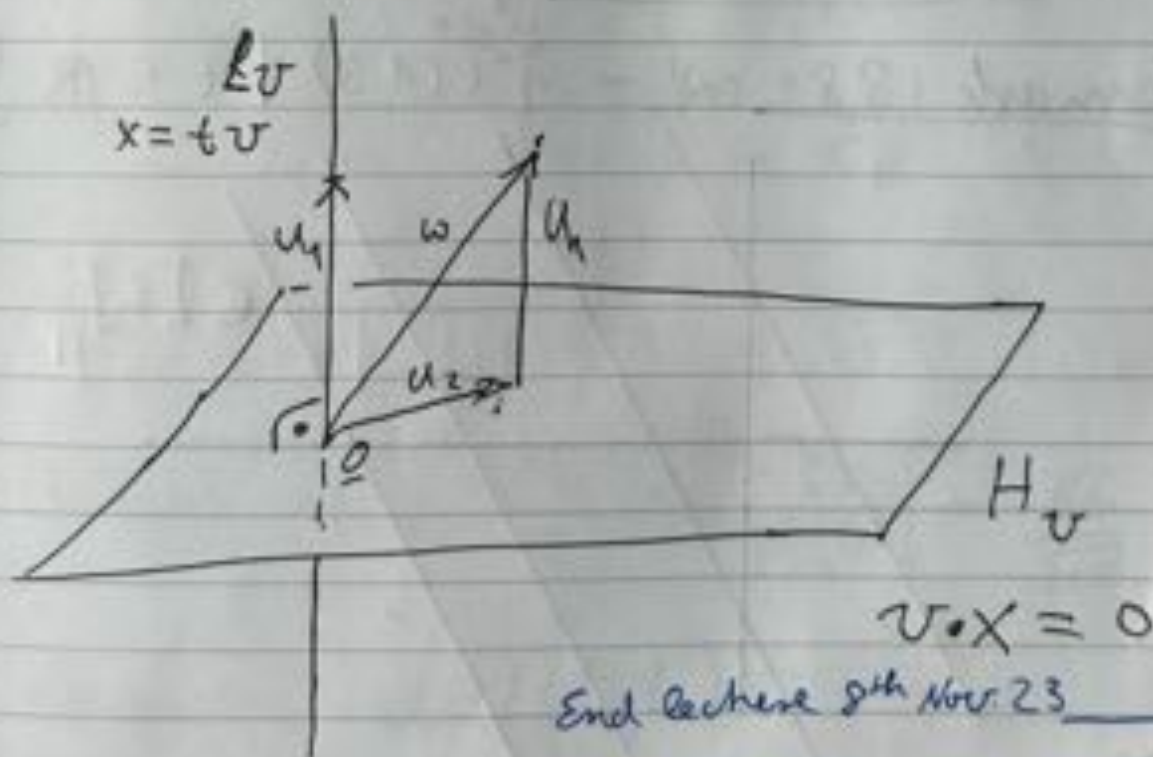
(c) The "Projection Theorem"

(Proposition 11.7) states that for v ,

$\in \mathbb{R}^n \setminus \{\vec{0}\}$ and $w \in \mathbb{R}^n$

$\exists! u_1, u_2 \in \mathbb{R}^n : w = u_1 + u_2$

$\wedge u_1 \parallel v \quad \wedge u_2 \perp v.$



→ See example class.

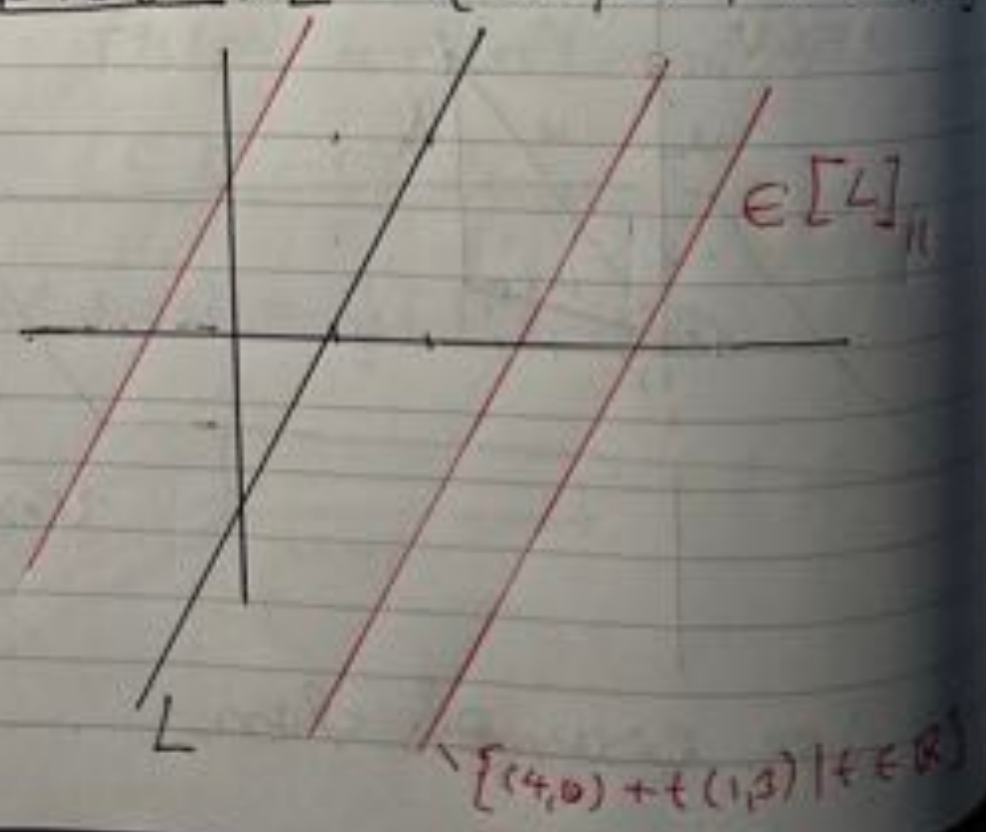
Notation: $u_1 = \text{proj}_v(w) = (w \cdot v_{\text{norm}}) v_{\text{norm}}$

Def 137: Two hyperplanes H_1, H_2 are called parallel ($H_1 \parallel H_2$) if

$\exists v \in \mathbb{R}^n \setminus \{0\}$: v is normal to H_1 and H_2 .

The set $[H_1]_{\parallel} = \{H \in \mathbb{R}^n \mid H \text{ hyperplane } \parallel H_1\}$ is called the parallel class of H_1 .

Remark 138: $\text{col} L = \{ \overset{(1,3)^T}{t} \in (1,3) \mid t \in \mathbb{R} \}$



(b) Give an example for a parallel class of planes in \mathbb{R}^3 .

(c) In (a): $P_0 = (5, -1) \in L + (4, -1)$
 $\underbrace{\hspace{10em}}_{=: L_0}$

Consider normal eqn^s:

$$L: -3x + y = -3$$

$$L_0: -3x + y = -16$$

normalize $(-3, 1) \rightarrow \frac{1}{\sqrt{10}}(-3, 1)$

$$L: \frac{-3}{\sqrt{10}}x + \frac{1}{\sqrt{10}}y = \frac{-3}{\sqrt{10}}$$

$$L_0: \frac{-3}{\sqrt{10}}x + \frac{1}{\sqrt{10}}y = \frac{-16}{\sqrt{10}}$$

What is $\left| \frac{-16}{\sqrt{10}} - \frac{(-3)}{\sqrt{10}} \right| = \frac{13}{\sqrt{10}}?$

Answer: $\text{dist}(P_0, L) = \frac{13}{\sqrt{10}}$.

$$\begin{aligned}
 \underline{\text{Prf:}} \quad \text{dist}(P_0, L) &= \left| \frac{1}{\sqrt{10}} (-3, 1) \cdot \overline{(4, 0)} \right| \\
 &= \frac{1}{\sqrt{10}} |(-3, 1) \cdot (4, -1)| \\
 &= \frac{1}{\sqrt{10}} |(-12 - 1)| = \frac{13}{\sqrt{10}} \quad \square
 \end{aligned}$$

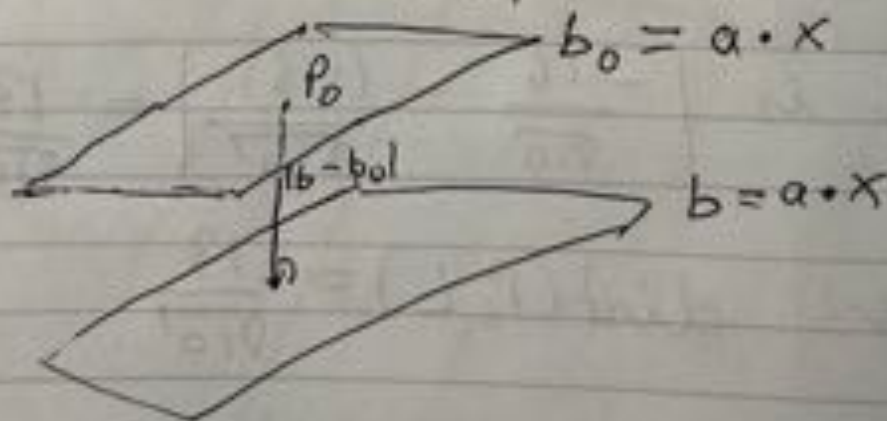
Theorem 139 (Distance Theorem)

Let H be a hyperplane in \mathbb{R}^n
given by

$a \cdot x = b$, $a \in \mathbb{R}^n \setminus \{0\}$, $b \in \mathbb{R}$
such that $\|a\| = 1$.

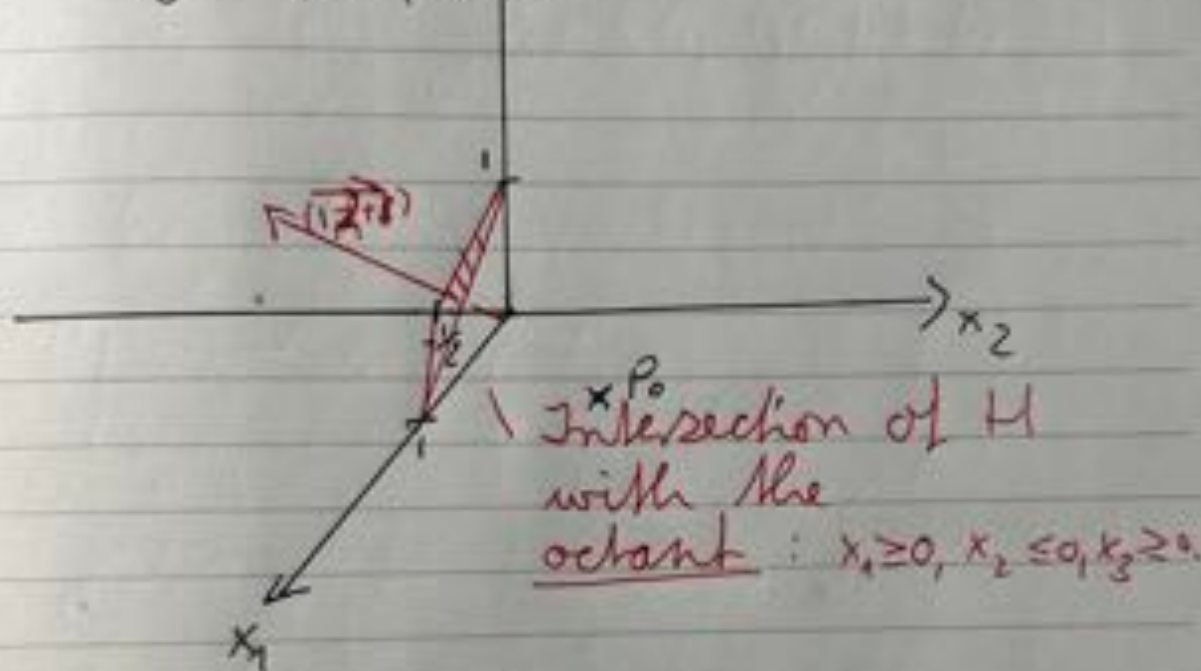
Take $P_0 \in \mathbb{R}^n$ with coordinates
 $x_0 = (x_{01}, x_{02}, \dots, x_{0n})$.

Then $\text{dist}(P_0, H) = |b - a \cdot x_0|$



Example 140: $\mathbb{R}^3 \supseteq H: (1, -2, 1) \cdot X = 1$

$$P_0 = (1, 1, 0)$$



$$\begin{aligned} \text{dist}(P_0, H) &= \left| \frac{1}{\sqrt{6}} - \frac{(1, 1, 0) \cdot (1, -2, 1)}{\sqrt{6}} \right| \\ &= \frac{1}{\sqrt{6}} |1 - (-1)| = \frac{2}{\sqrt{6}}. \end{aligned}$$

III 5. Geometry of linear systems

Def 141: A line in \mathbb{R}^n is a set of the form $L(P_0, P_1) = \{ tP_0 + (1-t)P_1 \mid t \in \mathbb{R} \}$ with $P_0, P_1 \in \mathbb{R}^n$ ($P_0 \neq P_1$).

A plane in \mathbb{R}^n is a set of the form $E(P_0, P_1, P_2) = \{ tP_0 + sP_1 + (1-t-s)P_2 \mid t, s \in \mathbb{R} \}$

for $P_0, P_1, P_2 \in \mathbb{R}^n$ ~~all~~ pairwise different such that $\overrightarrow{P_0 P_1} \neq \overrightarrow{P_0 P_2}$

Example 142:

(a) $P_0 = (1, 0, 0)$, $P_1 = (1, 1, 1)$ in \mathbb{R}^3



(b) $Q_0 = (1, 0, 0, 0)$, $Q_1 = (1, 1, 0, 0)$
 $Q_2 = (0, 0, 1, 1)$ in \mathbb{R}^4 .

$E(Q_0, Q_1, Q_2)$

Remark 143: (ways to describe lines and planes.)

We refer to Example 142 (a), (b).

way	line	plane
vector form	$P_0 + t \vec{v}, t \in \mathbb{R}$ (with $\vec{v} \neq 0$) $\underline{\text{Ex:}} (1, -1, -1) + t(0, 1, 1)$ $t \in \mathbb{R}$	$P_0 + t w + s u,$ $t, s \in \mathbb{R}$ (with $w, u \neq 0$ and $w \wedge u$) $\underline{\text{Ex:}} (1, 0, 0, 0)$ $+ t(0, 1, 0, 0) + s(-1, 0, 1, 1)$ $t, s \in \mathbb{R}$
using parametric equations	$x_1 = x_{01} + t v_1$ $x_2 = x_{02} + t v_2$ \vdots $x_n = x_{0n} + t v_n$ $\underline{\text{Ex:}} x_1 = 1, x_2 = -1 + t$ $x_3 = -1 + t$	$x_1 = x_{01} + t w_1 + s u_1$ \vdots $x_n = x_{0n} + t w_n + s u_n$ $\underline{\text{Ex:}} x_1 = 1 + (-1)t, x_2 = t$ $x_3 = t, x_4 = t$

as intersection
of hyper-
planes

$$L = H_1 \cap \dots \cap H_{n-1} \quad E = H_1 \cap \dots \cap H_{n-1}$$

~~$$L = H_1 \cap \dots \cap H_{n-1}$$~~

~~$$E = H_1 \cap \dots \cap H_{n-1}$$~~

Ex:

$$L = H_1 \cap H_2$$

$$E = H_1 \cap H_2$$

$$H_1 = \{x \in \mathbb{R}^3 \mid (1, 0, 0) \cdot x = 1\}$$

$$H_1 = \{x \in \mathbb{R}^4 \mid (1, 0, 1, 0) \cdot x = 1\}$$

$$H_2 = \{x \in \mathbb{R}^3 \mid (0, 1, -1) \cdot x = 0\}$$

$$H_2 = \{x \in \mathbb{R}^4 \mid (0, 0, 1, -1) \cdot x = 0\}$$

Example 144: (i) $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$

$$\text{sol}(A, b) := \{x \in \mathbb{R}^n \mid Ax = b\}$$

$$= \text{sol}(r_1, b_1) \cap \text{sol}(r_2, b_2) \cap \dots \cap \text{sol}(r_m, b_m)$$

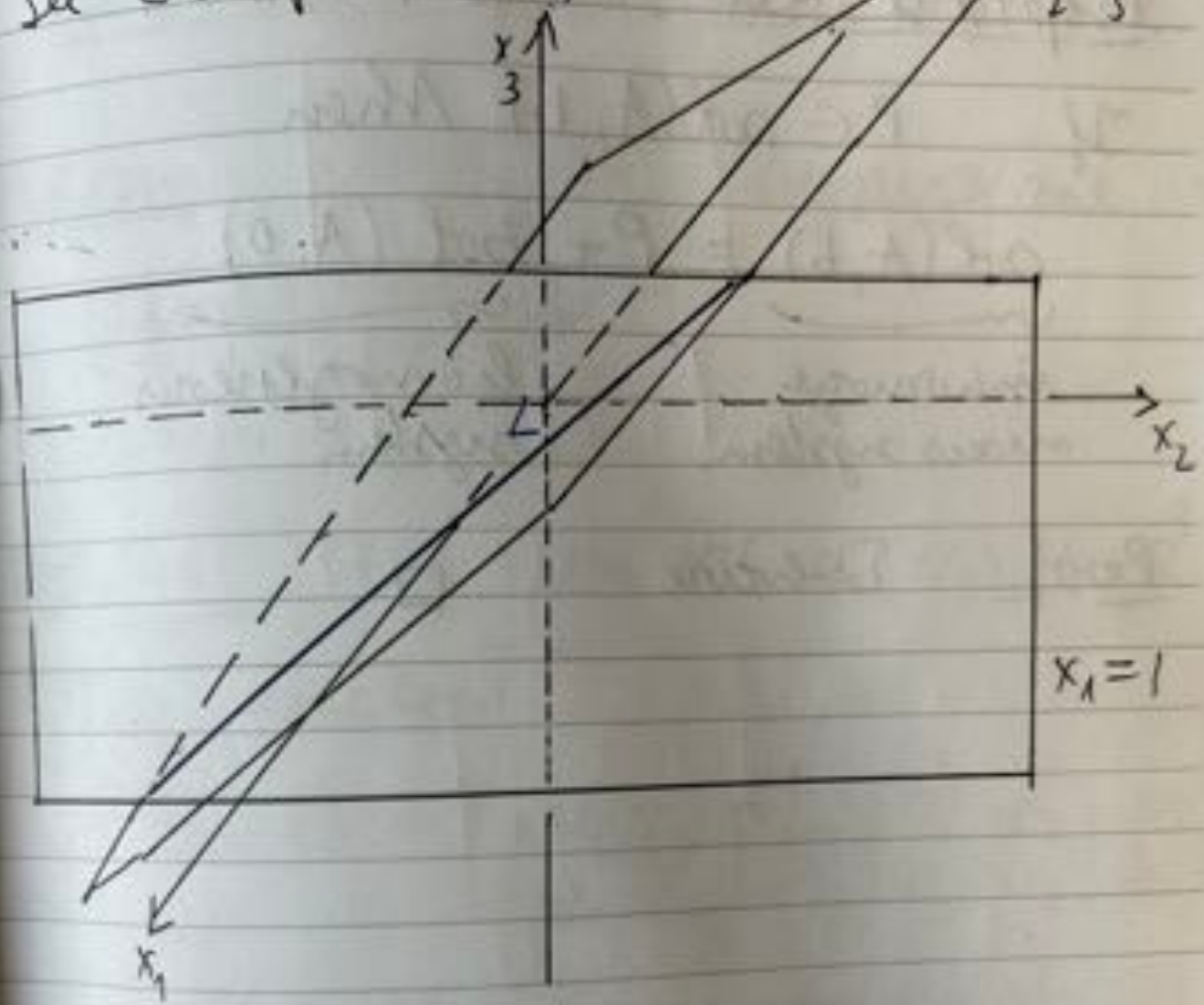
where

$$A = \begin{pmatrix} r_1 \\ \vdots \\ r_m \end{pmatrix}$$

(rows)

Suppose that all $r_i \neq (0, \dots, 0)$
 \Rightarrow all $\text{sol}(r_i, b_i)$ are hyperplanes

See Example 142(a)



$$A = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & -1 \end{pmatrix} \quad b = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\text{sol}(A, b) = \text{sol}((1, 0, 0), 1) \cap \text{sol}((0, 1, -1), 0)$$

(ii)

$$A = \begin{pmatrix} 1 & -1 \\ 0 & 1 \\ 1 & 0 \end{pmatrix} \quad b = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\text{sol}(A, b) = \emptyset$$

Prop 145: Let $A \in \mathbb{R}^{m \times n}$, $b \in \mathbb{R}^m$

If $P \in \text{sol}(A, b)$ then

$$\text{sol}(A, b) = P + \text{sol}(A, 0)$$

inhomogeneous system.

homogeneous system

Proof: Exercise

□

III.6. Cross product

Problem: $H \subseteq \mathbb{R}^3$ hyperplane

Find $\vec{n} \perp H$
 $\vec{n} \neq \vec{0}$

Def 146: Let $v = (v_1, v_2, v_3), w \in \mathbb{R}^3$

The vector

$$v \times w := \begin{pmatrix} |v_2 v_3| & -|v_1 v_3| & |v_1 v_2| \\ |w_2 w_3| & -|w_1 w_3| & |w_1 w_2| \end{pmatrix}$$

is called the cross product of v and w .

□ If we have $\vec{i} = (1, 0, 0)$ $\vec{j} = (0, 1, 0)$

$\vec{k} = (0, 0, 1)$ then formally

$$v \times w = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ v_1 & v_2 & v_3 \\ w_1 & w_2 & w_3 \end{vmatrix}$$

Example 147:

$$c) \quad \vec{i} \times \vec{j} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{vmatrix}$$

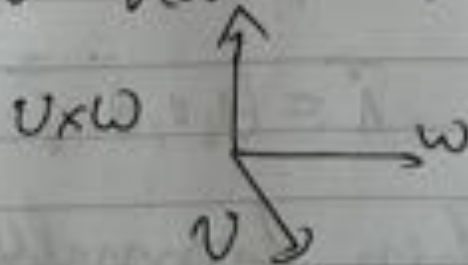
$$= \begin{vmatrix} 0 & 0 \\ 1 & 0 \end{vmatrix} \vec{i} - \begin{vmatrix} 1 & 0 \\ 0 & 0 \end{vmatrix} \vec{j} + \begin{vmatrix} 1 & 0 \\ 0 & 1 \end{vmatrix} \vec{k}$$

$$= \vec{k} = (0, 0, 1)$$

$$\vec{j} \times \vec{i} = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{vmatrix} = -\vec{k}$$

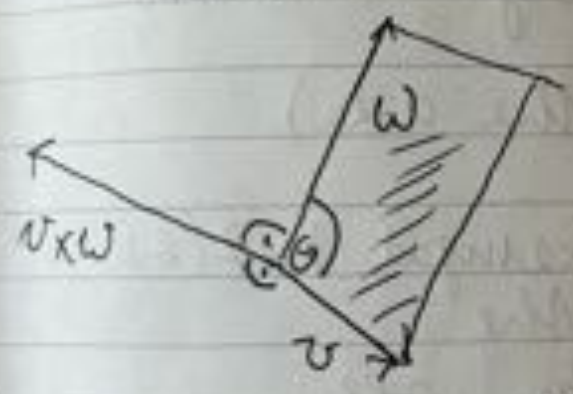
$$= (0, 0, -1)$$

Right hand rule



(b) $v = (1, 1, 0), w = (0, -2, 2)$

$$v \times w = \begin{vmatrix} \vec{i} & \vec{j} & \vec{k} \\ 1 & 1 & 0 \\ 0 & -2 & 2 \end{vmatrix} = (2, -2, 2)$$



$$\begin{aligned} \text{area} &= \|v\| \|w\| \sin \theta \\ &= \sqrt{2} \cdot 2\sqrt{2} \cdot \frac{\sqrt{3}}{2} \\ &= \underline{\underline{2\sqrt{3}}} \end{aligned}$$

(where $\sin \theta = \sqrt{1 - \cos^2 \theta}$)

$$\begin{aligned} &= \sqrt{1 - \left(\frac{v \cdot w}{\|v\| \|w\|}\right)^2} \\ &= \sqrt{1 - \left(\frac{-2}{\sqrt{2} \cdot 2\sqrt{2}}\right)^2} \\ &= \frac{\sqrt{3}}{2} \end{aligned}$$

$$\|v \times w\| = \sqrt{4+4+4} = 2\sqrt{3}$$

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Prop 148: Let $v, w \in \mathbb{R}^3 - \{0\}$

Then $v \times w$ has direction given by the right hand rule and

$\|v \times w\| = \text{area of the parallelogram spanned by } v \text{ and } w.$

Proof: (only for the area)

By the idea of Example 147(b) it follows from the Lagrange identity, see next proposition \square

Prop 149: (cross product and dot product.)

$u, v, w \in \mathbb{R}^3$

(a) u and v are \perp to $u \times v$

(b) $u \times (v \times w) = (u \cdot w)v - (u \cdot v)w$

(c) (Lagrange identity)

$$\|u \times v\|^2 = \|u\|^2 \|v\|^2 - (u \cdot v)^2$$

Proof: (a) $u \cdot (u \times v) = \begin{vmatrix} u_1 & u_2 & u_3 \\ u_1 & u_2 & u_3 \\ v_1 & v_2 & v_3 \end{vmatrix} = 0$

 $v \perp (u \times v)$ similarly

(b) Exercise.

$$(c) \|u \times v\|^2 = (u_2 v_3 - v_2 u_3)^2 + (u_1 v_3 - v_1 u_3)^2 + (u_1 v_2 - u_2 v_1)^2$$

$$= u_2^2 v_3^2 + v_2^2 u_3^2 - 2u_2 u_3 v_2 v_3$$

$$+ u_1^2 v_3^2 + u_3^2 v_1^2 - 2u_1 u_3 v_1 v_3$$

$$+ u_1^2 v_2^2 + u_2^2 v_1^2 - 2u_1 u_2 v_1 v_2$$

$$= \|u\|^2 \|v\|^2 - u_1^2 v_1^2 - u_2^2 v_2^2 - u_3^2 v_3^2 - \sum_{i \neq j} (u_i v_i)(u_j v_j)$$

$$= \|u\|^2 \|v\|^2 - (u \cdot v)^2 \quad \square$$

Prop 1.50: Given $u, v, w \in \mathbb{R}^3$

The map $[, ,] : \mathbb{R}^3 \times \mathbb{R}^3 \times \mathbb{R}^3 \rightarrow \mathbb{R}$

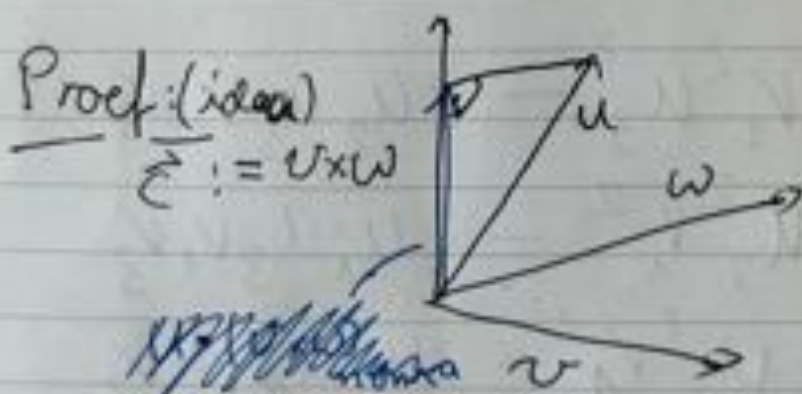
$$(u, v, w) \mapsto u \cdot (v \times w) = \begin{vmatrix} u \\ v \\ w \end{vmatrix}$$

" "
[u, v, w]

is called scalar triple product
and

$[u, v, w]$ is the ^{signed} volume

of the parallelepiped spanned
by u, v, w .



$$(u \cdot \vec{c}) \vec{c}_{\text{norm}} =: \vec{d} = \text{proj}_{\vec{c}}(u)$$

So $[u, v, w] = \|\vec{d}\| \cdot \|\vec{c}\| = \text{volume of the parallelepiped}$ \square