

$$\text{Under } \mathbb{R}^2 \otimes \mathbb{R}^2 \xrightarrow{\Phi} M_2(\mathbb{R}) \\ v \otimes w \mapsto vw^t$$

The elementary tensors correspond to matrixes of rank ≤ 1 , but

$$\Phi(e_1 \otimes e_2 + e_2 \otimes e_1) = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

has rank 2.

A tensor is a finite sum (!) of elementary tensors.

(b) Decompose $A = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}$

using the smallest number of elementary tensors.

$$\begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix} = \begin{pmatrix} 1 & 1 \\ 1 & 1 \end{pmatrix} + \begin{pmatrix} 0 & 0 \\ 0 & 2 \end{pmatrix}$$

$$= \Phi\left(\begin{pmatrix} 1 \\ 1 \end{pmatrix} \otimes \begin{pmatrix} 1 \\ 1 \end{pmatrix}\right) + \Phi\left(\begin{pmatrix} 0 \\ 2 \end{pmatrix} \otimes \begin{pmatrix} 0 \\ 1 \end{pmatrix}\right)$$

$$= \Phi((e_1 + e_2) \otimes (e_1 + e_2) + 2e_2 \otimes e_2)$$

Def 3.19: Let V be finite dimensional real vector space and $k \in \mathbb{N}$.

Let M be the real subspace of $\underbrace{V \otimes \dots \otimes V}_k = V^{\otimes k}$

generated by the elements set

$$\{v_1 \otimes v_2 \otimes \dots \otimes v_k \mid v_i \in V,$$

$$\exists i, j \text{ } i \neq j : v_i = v_j\}$$

$\Lambda^k V := \frac{V^{\otimes k}}{M}$ is called

power

the k -th exterior ~~product~~ of V .

We write $v_1 \wedge \dots \wedge v_k$ for the class $[v_1 \otimes \dots \otimes v_k]_M$.

Prop 3.20: Let V be a finite dim real vector space. Then $\Lambda^k(V^*)$ is \mathbb{R} -linear isomorphic to $\text{Alt}^k(V)$ via a map

$$\Phi: \text{Alt}^k(V) \rightarrow \Lambda^k(V^*)$$

which satisfies

$$\Phi(\underbrace{f_1 \wedge \dots \wedge f_k}_{\text{wedge product}}) = \underbrace{f_1 \wedge \dots \wedge f_k}_{\text{"}}$$

wedge product
for alternating
forms

$$[f_1 \otimes \dots \otimes f_k]$$

Proof: Define Φ as above on a basis
of $\text{Alt}^k(V)$. Show that Φ
is injective. (Exercise!) \square

Remark 3.21: (transformation matrix)

Let M and N be manifolds exp. real
and $f: M \rightarrow N$ C^∞ . Take charts (φ, U)
and (ψ, V) of M and N resp. s.t.
 $f(U) \subseteq V$. (x_1, \dots, x_m) . Then for $P \in U$:

$$\left((T_P f) \left(\frac{\partial}{\partial x_1} \right), \dots, (T_P f) \left(\frac{\partial}{\partial x_m} \right) \right)$$

$$= A \left(\frac{\partial}{\partial y_1} \right), \dots, \frac{\partial}{\partial y_n} A^{(P)}$$

$$\text{for } A = \begin{pmatrix} \frac{\partial t_1}{\partial x_1} & \dots & \frac{\partial t_1}{\partial x_m} \\ \vdots & \ddots & \vdots \\ \frac{\partial t_n}{\partial x_1} & \dots & \frac{\partial t_n}{\partial x_m} \end{pmatrix}$$

where $t_i := \gamma_i \circ f : U \rightarrow \mathbb{R}^n$.

$$\text{Proof: } (T_p f) \left(\frac{\partial}{\partial x_i} (p) \right) = (T_p f) ([p, \varphi, e_i])$$

$$= [f(p), \psi, \underbrace{D(\psi \circ f \circ \varphi^{-1})}_{\text{Jacobi matrix of } \psi \circ f \circ \varphi^{-1} \text{ at } \varphi(p)} (\varphi(p)) e_i]$$

Jacobi matrix of
 $\psi \circ f \circ \varphi^{-1}$ at $\varphi(p)$.

$$= [f(p), \psi, \sum_{j=1}^n e_j \underbrace{\frac{\partial (\psi \circ f \circ \varphi^{-1})}{\partial x_i}}_{\text{partial derivatives}} (\varphi(p))]]$$

$$= [f(p), \psi, \sum_{j=1}^n \underbrace{\frac{\partial (\gamma_j \circ f)}{\partial x_i}}_{\text{derivation w.r.t. } x_i} (p) e_j]$$

derivation ~~is~~ w.r.t.
 x_i .

$$= \sum_{j=1}^n \frac{\partial f_j}{\partial x_i}(p) [f(p), \psi, e_j]$$

$$= \sum_{j=1}^n \underbrace{\frac{\partial (f_j(p))}{\partial y_j}}_{\in T_p(p)^N} \cdot \underbrace{\frac{\partial f_j}{\partial x_i}(p)}_{\in \mathbb{R}} \quad \square$$

Def 3.22: Let V be a f.d. \mathbb{R} -v.s.

(a) A k -tensor is a k -linear function
 $f: V \times \dots \times V \rightarrow \mathbb{R}$

(i.e. an element of $V^* \otimes \dots \otimes V^*$
 after identifying $\text{mult}^k(V, \mathbb{R})$
 with $(V^*)^{\otimes k}$.)

(b) An alternating k -form $f \in \text{Alt}^k(V)$
 is also called alternating k -tensor

(We identify $\Lambda^k(V^*)$ with $\text{Alt}^k(V)$)

It is also called k -covector.

Notation 3.23: Let M be a mf. and $p \in M$.

We write T_p^*M for $(T_p M)^*$, the dual vector space of $T_p M$.

Def 3.24: Let M be a mf. A k -covector field on M (also differential k -form on M , k -form on M)

is a map $\omega : M \longrightarrow \Lambda^k(T^*M)$
such that $\omega(p) \in \Lambda^k(T_p^*M)$, for all $p \in M$.

Example 3.25: Let (φ, U) be a chart on M .

$$(x_1, \dots, x_m)$$

Let $\omega_1(p), \dots, \omega_m(p)$ be the dual basis
of $\left(\frac{\partial}{\partial x_1}(p), \dots, \frac{\partial}{\partial x_m}(p) \right)$.

Then $\omega_i : U \longrightarrow \Lambda^1(T^*U) = \Lambda^1(T^*M)$
are 1-covector fields on U .
$$T^*M$$

We can obtain $\omega_1, \dots, \omega_m$ in a different way.

Def 3.26: Let $f \in C^\infty(M, \mathbb{R})$. Using the derivative $Tf: TM \rightarrow T\mathbb{R}$ of f , we obtain a 1-form as follows

$$TM \xrightarrow{Tf} T\mathbb{R} \xrightarrow{\cong} \mathbb{R} \times \mathbb{R} \xrightarrow{\text{pr}_2} \mathbb{R}$$

$$[p, \text{id}, v] \mapsto [p, v]$$

$$\underbrace{\hspace{15em}}_{df}$$

The map $df: M \rightarrow T^*M$ is called differential of f

Remark 3.27:

(i) We have in coordinates $\varphi = (x_1, \dots, x_n)$:

$$(T_p f)(X) = (df)_p(X) \cdot \frac{\partial}{\partial x_i} f(p),$$

$X \in T_p M$, using the chart $(\text{id}_{\mathbb{R}}, \mathbb{R})$
on \mathbb{R}

(ii) Given coordinates $\varphi = (x_1, \dots, x_m)$
 we have $x_1, \dots, x_m \in C^\infty(U, \mathbb{R})$.

Thus dx_1, \dots, dx_m are 1-forms
 on U .

Claim: $(dx_1)_p, \dots, (dx_m)_p$ is the
 dual basis of $\frac{\partial}{\partial x_1}(p), \dots, \frac{\partial}{\partial x_m}(p)$.

Proof:

$$\left(T_p x_i \left(\frac{\partial}{\partial x_1}(p) \right), T_p x_i \left(\frac{\partial}{\partial x_2}(p) \right), \dots, T_p x_i \left(\frac{\partial}{\partial x_m}(p) \right) \right)$$

$$= \frac{\partial}{\partial t} \Big|_{x_i(p)} \left(\frac{\partial x_i^t}{\partial x_1}, \dots, \frac{\partial x_i^t}{\partial x_m} \right)$$

By Remark 3.21.

Now $\frac{\partial x_i}{\partial x_j}(p) = \delta_{ij}, p \in U. \quad \square$

Def 3.28: (The cotangent bundle on M)

$$\begin{aligned} \text{let } M \text{ be a mf. } \quad T^*M &:= \bigsqcup_P T_P^*M \\ &= \left\{ (p, f) \mid p \in M \text{ and } f \in T_P^*M \right\} \end{aligned}$$

is called the cotangent bundle on M

We define a differential structure on T^*M using charts $(\varphi = (x_1, \dots, x_m), U)$ of M via:

$$\begin{aligned} T^*M \supseteq T^*U &\xrightarrow{\sim} U \times \mathbb{R}^m \\ (p, \sum_{i=1}^m \lambda_i (dx_i)_p) &\longmapsto (\varphi(p), \lambda_1, \dots, \lambda_m) \end{aligned}$$

Which matrix is the transformation matrix for a coordinate change?

(Exercise!)

We have more vector bundles:

- The tensor bundle of type (p, q) :

$$(TM)^{\otimes p} \otimes (T^*M)^{\otimes q} \longrightarrow M$$

- The k -th exterior power of the cotangent bundle on M :

$$\Lambda^k(T^*M) \longrightarrow M$$

The tangent bundle is the tensor bundle of type $(1, 0)$.

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Def 3.29: We call a differential k -form ω smooth if $\omega \in C^\infty(M, \Lambda^k(T^*M))$

(Recall: For $\Lambda^k(T^*M)$ the local frame is given by

$$\{ dx_{i_1} \wedge \dots \wedge dx_{i_k} \mid 1 \leq i_1 < \dots < i_k \leq m \}$$

ordered in a lexicographic way

(Ex: $dx_1 \wedge dx_3 \wedge dx_5 \wedge dx_6$

$< dx_1 \wedge dx_3 \wedge dx_4 \wedge dx_7$)

Notation 3.30: We write $\Omega^k(M)$

for the set of smooth differential k -forms, $k = 0, 1, 2, \dots$

Then $\Omega^0(M) = C^\infty(M, \mathbb{R})$

Example 3.31: (a) Find $\omega \in \Omega^1(\mathbb{R}^2 \setminus \{0\})$

which satisfies

$$(*) \begin{cases} \omega \left(-y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y} \right) \equiv 1 \text{ and} \\ \omega \left(x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right) \equiv 0. \end{cases}$$

Solution: Ansatz

$$\omega = a dx + b dy$$

$$(*) \Leftrightarrow \begin{cases} -ay + bx \equiv 1 \\ ax + by \equiv 0 \end{cases}$$

$$\Leftrightarrow a = \frac{-y}{x^2+y^2}, \quad b = \frac{x}{x^2+y^2}$$

Thus the solution is

$$\omega = \frac{-y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$$

(b) We have a map

$$\begin{aligned} d: \Omega^0(M) &\longrightarrow \Omega^1(M) \\ f &\longmapsto df. \end{aligned}$$

Is there an $f \in \Omega^0(M)$ ($M = \mathbb{R}^2 - \{0\}$) such that $df = \omega$?

If yes then:

$$\nabla f \cdot \begin{pmatrix} -y & x \\ x & y \end{pmatrix} = (1, 0)$$

$$\Leftrightarrow \nabla f = (-y, +x) \cdot \frac{1}{x^2 + y^2}$$

$$\begin{pmatrix} -y & x \\ x & y \end{pmatrix}^{-1} = \begin{pmatrix} y & -x \\ -x & -y \end{pmatrix} \cdot \frac{1}{-x^2 - y^2}$$

Another way: $df = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy = \frac{-y}{x^2 + y^2} dx + \frac{x}{x^2 + y^2} dy$

$$\Rightarrow \frac{\partial f}{\partial x} = \frac{-y}{x^2 + y^2} \quad \text{and} \quad \frac{\partial f}{\partial y} = \frac{x}{x^2 + y^2}$$

Put $g(t) = f(\cos t, \sin t)$ and $c(t) = (\cos t, \sin t)$.

$$\begin{aligned} \Rightarrow \int_0^{2\pi} g'(t) dt &= \int_0^{2\pi} \nabla f(c(t)) \cdot c'(t) dt \\ &= \int_0^{2\pi} 1 dt = 2\pi \end{aligned}$$

$$\text{and } \int_0^{2\pi} g'(t) dt = g(2\pi) - g(0) = 0. \quad \underline{\underline{\text{?}}}$$

(c) We have another map

$$d: \Omega^1(\mathbb{R}^2 - \{0\}) \rightarrow \Omega^2(\mathbb{R}^2 - \{0\})$$

given by

$$d(a dx + b dy) := da \wedge dx + db \wedge dy$$

So we have

$$\Omega^0(\mathbb{R}^2 - \{0\}) \xrightarrow{d_0} \Omega^1(\mathbb{R}^2 - \{0\}) \xrightarrow{d_1} \Omega^2(\mathbb{R}^2 - \{0\})$$

The "de Rham complex of $\mathbb{R}^2 - \{0\}$ "

(1) We have $d^2 = 0$.

Proof: $d(d f)$

$$d\left(\frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy\right)$$

$$d\left(\frac{\partial f}{\partial x}\right) \wedge dx + d\left(\frac{\partial f}{\partial y}\right) \wedge dy$$

$$\left(\frac{\partial^2 f}{\partial x^2} dx + \frac{\partial^2 f}{\partial y \partial x} dy\right) \wedge dx + \left(\frac{\partial^2 f}{\partial x \partial y} dx + \frac{\partial^2 f}{\partial y^2} dy\right) \wedge dy$$

$$\frac{\partial^2 f}{\partial y \partial x} dy \wedge dx + \frac{\partial^2 f}{\partial x \partial y} dx \wedge dy$$

$= 0$

\square

(c2) The complex is not exact in the middle, because

$$\omega = \frac{-y}{x^2+y^2} dx + \frac{x}{x^2+y^2} dy$$

is in the kernel of d , but not in the image of d_0 .

Pf: By (b) : $\omega \notin \text{im } d_0$.

$$d\omega = d\left(\frac{-y}{x^2+y^2}\right) \wedge dx + d\left(\frac{x}{x^2+y^2}\right) \wedge dy$$

$$= \left(\frac{+2xy}{(x^2+y^2)^2} dx + \frac{y^2-x^2}{(x^2+y^2)^2} dy \right) \wedge dx$$

$$+ \left(\frac{y^2-x^2}{(x^2+y^2)^2} dx + \frac{(-2yx)}{(x^2+y^2)^2} dy \right) \wedge dy$$

$$= \frac{y^2-x^2}{(x^2+y^2)^2} (dy \wedge dx + dx \wedge dy)$$

$$= 0 \quad \square$$

Thus M has nontrivial first de Rham cohomology

$$H_{dR}^1(\mathbb{R}^2 \setminus \{0\}) := \ker d_1 / \text{im } d_0 \cong \mathbb{R}$$

In fact $H^1_{dR}(\mathbb{R}^2 - \{0\}) \cong \mathbb{R}$ via

$$[\omega] \longmapsto \frac{1}{2\pi} \int_0^{2\pi} \omega(c'(t)) dt$$

Proof: Surjectivity: $1 \in \text{im } \Phi$ by

Injectivity: let $\omega \in \ker \Phi$.

$$\text{But } f(P) := \int_{c_P} \omega(c'_P(t)) dt$$

where

c_P is a curve from $(1,0)$ to P going first

to $e^{i\varphi}$ via c and then to P on a segment.



Instead of c we could have taken c^{-1} to define f , ~~so~~ because $w \in \ker \Phi$:

$$\left(\int_{c_p} w(c'_p(t)) dt = \int_{\tilde{c}} w(\tilde{c}'(t)) dt \right. \\ \left. = \int_c w(c'(t)) dt = 0. \right)$$

Now it is an easy exercise to show that $df = w$ \square

(d) Find $\Omega^1(S^1)$.

We consider S^1 as a submf of \mathbb{R}^2

$$T_p S^1 \subseteq T_p \mathbb{R}^2 \\ \left\{ \begin{array}{l} a \frac{\partial}{\partial x}(p) + b \frac{\partial}{\partial y}(p) \mid a, b \in \mathbb{R} \\ ax_p + by_p = 0 \end{array} \right.$$

$$\mathbb{R} \left(-y_p \frac{\partial}{\partial x}(p) + x_p \frac{\partial}{\partial y}(p) \right)$$

$$\Omega^1(S^1) = C^\infty(S^1) ((-y dx + x dy)|_{TS^1}).$$

Remark 3.40: Let M be the Möbius strip and N be the submanifold obtained by removing a cutting segment from M .



$$N = M \setminus \text{segment}$$

Then $\Omega^1(M) \xrightarrow{\text{res}} \Omega^1(N)$ is not surjective.

We have to introduce the exterior derivative and the pullback of differential form under a C^∞ -map rigorously.

Def 3.41: A quadruple $(A, +: A \times A \rightarrow A, \cdot: A \times A \rightarrow A, \odot: A \times A \rightarrow A)$ is called an \mathbb{R} -algebra if

(A1) $(A, +, \cdot)$ is an \mathbb{R} -v.s.

(A2) $(A, +, \odot)$ is a ring (possibly not commutative) and

(A3) $\forall r_1, r_2 \in \mathbb{R} \forall a_1, a_2 \in A$

$$\begin{matrix} (r_1 a_1) \odot (r_2 a_2) \\ \parallel \\ (r_1 r_2) \odot (a_1 \odot a_2) \end{matrix}$$

Ex. 3.42: (a) \mathbb{R} is an \mathbb{R} -algebra
 $(r, \odot r := r, r)$

(b) $M_n(\mathbb{R})$ is an \mathbb{R} -algebra
 using \cdot $r \cdot \underbrace{A}_{(a_{ij})} := (ra_{ij})_{ij}$
 $\cdot A \odot B^{(a_{ij})} = AB$.

(c) $C^\infty(M, \mathbb{R})$ is an \mathbb{R} -algebra
 with $(f \odot g)(p) := f(p)g(p)$.

(d) $\Omega^*(M) := \bigoplus_{i=0}^{\infty} \Omega^i(M)$
 $= \bigoplus_{i=0}^m \Omega^i(M)$

is an \mathbb{R} -algebra via

$$\omega \odot \tau := \omega \wedge \tau$$

"algebra of differential forms
 on M ".

Def 3.43: Let A be an \mathbb{R} -algebra
 and let $A_i \leq A$ be subvector
 spaces ($i \in \mathbb{N}_0$) such that

$A = \bigoplus_{i=0}^{\infty} A_i$; The \mathbb{R} -algebra A is called a graded \mathbb{R} -algebra with grading $\bigoplus_{i=0}^{\infty} A_i$ if

(GA1) $A = \bigoplus_{i=0}^{\infty} A_i$

(GA2) $\forall i, j \in \mathbb{N}_0 : \forall a \in A_i, \forall b \in A_j : a \odot b \in A_{i+j}$.

End of Lecture 31.03.2023

Example 3.44:

(a) $\mathbb{R}[X, Y]$ is a graded algebra with grading

$$\mathbb{R}[X, Y] = \bigoplus_{i=0}^{\infty} \mathbb{R}[X, Y]_i$$

$$\mathbb{R}[X, Y]_i := \{ P \in \mathbb{R}[X, Y] \mid P=0 \text{ or } P \text{ is a homogeneous polynomial of degree } i \}$$

$$= \sum_{\substack{s, t \in \mathbb{N}_0 \\ s+t=i}} \mathbb{R} X^s Y^t$$